

System MICRO

SM-AIO | | Manual

HB400 | SM-AIO | | en | 25-10

Analog signal modules - SM M3x



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1 General

1.1 About this manual

Objective and contents

The manual describes the analog signal modules SM M3x of the System MICRO.

- It describes the structure, configuration and application.
- The manual is targeted at users with good basic knowledge in automation technology.
- The manual does not replace sufficient basic knowledge of automation technology or sufficient familiarity with the specific product.
- The manual consists of chapters. Each chapter describes a completed topic.
- For guidance, the manual provides:
 - An overall table of contents at the beginning of the manual
 - References with page numbers

Documentation

In the context of the use of the pertinent Yaskawa product, the manual is to be made accessible to the pertinent qualified personnel in:

- Project engineering
- Installation department
- Commissioning
- Operation

Icons and headings

Important passages in the text are highlighted by following icons and headings:



DANGER

- Immediate danger to life and limb of personnel and others.
- Non-compliance will cause death or serious injury.



CAUTION

- Hazardous situation to life and limb of personnel and others. Non-compliance may cause slight injuries.
- This symbol is also used as warning of damages to property.



NOTICE

- Designates a possibly harmful situation.
- Non-compliance can damage the product or something in its environment.



Supplementary information and useful tips.

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Download Center

By entering the product order number in the '*Download Center*' at www.yaskawa.eu.com, the pertinent manuals, data sheets, declarations of conformity, certificates and other helpful information for your product can be found.

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1.3 Safety instructions

General safety instructions



DANGER

Danger to life due to non-compliance with safety instructions

Non-compliance with the safety instructions in the manual can result in serious injury or death. The manufacturer is not responsible for any injuries or damage to the equipment.



CAUTION

Before commissioning and operating the components described in this manual, it is essential to note the following:

- Modifications to the automation system must only be done in a voltage-free state!
- Connection and modification only by trained electricians
- National regulations and guidelines in the respective country of use must be observed and complied with (installation, protective measures, EMC, etc.)

Intended use

- It is the customer's responsibility to comply with all pertinent standards, codes, or regulations applicable to the use of the product, including those that apply when the Yaskawa product is used in combination with other products.
- The customer must confirm that the Yaskawa product is suitable for the customer's plant, machinery and equipment.
- If the Yaskawa product is used in a manner not specified by this manual, the protection provided by the Yaskawa product may be impaired and the use may result in material or immaterial damage.
- Contact Yaskawa to determine whether use is permitted in the following applications. If the use in the respective application is permissible, the Yaskawa product is to be used by considering additional risk assessments and specifications, and safety measures are to be provided to minimise the dangers in the event of a fault. Special caution is required and protective measures must be taken in the case of:
 - Outdoor use, use with possible chemical contamination or electrical interference, or use under conditions or in environments which are not described in product catalogs or manuals
 - Nuclear control systems, combustion systems, railway systems, aviation systems, automotive systems, medical devices, amusement machines and equipment that is specifically regulated by industry or government
 - Systems, machines and devices that can pose a risk to life or property
 - Systems that require a high degree of reliability, such as gas, water or electricity supply systems or systems that operate 24 hours a day
 - Other systems that require a similarly high level of security
- Never use the Yaskawa product in an application where failure of the product could cause serious danger to life, limb, health or property without first ensuring that the system is designed to provide the required level of safety with risk warnings and redundancy to avoid the realisation of such dangers and that the Yaskawa product is properly designed and installed.
- The connection examples and other application examples described in the product catalogs and manuals of Yaskawa are for reference purposes. Check the functionality and safety of the devices and systems actually to be used before using the Yaskawa product.
- To avoid accidental harm to third parties, read and understand all prohibitions on use and precautions, and operate the Yaskawa product correctly.

Field of application

- The Yaskawa product is not suited for use in life-support machines or systems.
- Please contact your Yaskawa representative or Yaskawa distributor if considering the use of the Yaskawa product for special purposes, such as machines or systems used in passenger cars, in medical, aircraft and aerospace applications, for power supply of networks, for electrical power distribution or for underwater applications.

**DANGER**

The device is not permitted for use

- in explosive environments (EX zone)

The system is designed and manufactured for proper use and use in accordance with the user manual and is designed for:

- Communication and process control
- general control and automation tasks
- for industrial use
- operation within the environmental conditions specified in the technical data
- installation in a cabinet

**DANGER**

If this Yaskawa product is used in applications where failure of the device can result in the loss of human life, a serious accident or physical injury, you must install appropriate safety devices.

- Death or serious injury can result if you do not install the safety devices properly.

Disclaimer

(1) The contractual and legal liability of Yaskawa and the legal representatives and vicarious agents of Yaskawa for compensation and reimbursement of expenses in relation to the content of this documentation is excluded or limited as follows:

a) For slightly negligent breaches of *Essential Contractual Duties* arising from the contractual obligation, for Yaskawa the amount of liability is limited to the foreseeable damage typical for the contract. '*Essential Contractual Duties*' are those duties that characterise the performance of the contract and on which the Yaskawa customer may reasonably rely.

(b) In each case, Yaskawa is not liable for (i) the slightly negligent breach of duties arising from the duties that are not *Essential Contractual Duties*, as well as (ii) force majeure, i.e. external events that have no operational connection and cannot be averted even by exercising the utmost care that can reasonably be expected.

(2) The aforementioned limitation of liability does not apply (i) in cases of mandatory statutory liability (in particular under the product liability law), (ii) if and to the extent that Yaskawa has assumed a guarantee or same as guaranteed procurement risk according to § 276 BGB, (iii) for culpably caused injuries to life, limb and/or health, also by representatives or vicarious agents, as well as (iv) in case of delay in the event of a fixed completion date.

(3) A reversal of the burden of proof is not associated with the provisions above.

Disposal

National rules and regulations apply to the disposal of the unit!

2 Basics and mounting

2.1 Safety notes for the user



DANGER

Protection against dangerous voltages

- When using System MICRO modules, the user must be protected from touching hazardous voltage.
- You must therefore create an insulation concept for your system that includes safe separation of the potential areas of ELV and hazardous voltage.
- Here, observe the insulation voltages between the potential areas specified for the System MICRO modules and take suitable measures, such as using PELV/SELV power supplies for System MICRO modules.

Handling of electrostatic sensitive modules

The modules are equipped with highly integrated components in MOS technology. These components are highly sensitive to over-voltages that occur, e.g. with electrostatic discharge. The following symbol is used to identify these hazardous modules:



The symbol is located on modules, module racks or on packaging and thus indicates electrostatic sensitive modules. Electrostatic sensitive modules can be destroyed by energies and voltages that are far below the limits of human perception. If a person who is not electrically discharged handles electrostatic sensitive modules, voltages can occur and damage components and thus impair the functionality of the modules or render the modules unusable. Modules damaged in this way are in most cases not immediately recognized as faulty. The error can only appear after a long period of operation. Components damaged by static discharge can show temporary faults when exposed to temperature changes, vibrations or load changes. Only the consistent use of protective devices and responsible observance of the handling rules can effectively prevent malfunctions and failures on electrostatic sensitive modules.

Shipping of modules

Please always use the original packaging for shipping.

Measurement and modification of electrostatic sensitive modules

For measurements on electrostatic sensitive modules the following must be observed:

- Floating measuring instruments must be discharged before use.
- Measuring instruments used must be grounded.

When modifying electrostatic sensitive modules, ensure that a grounded soldering iron is used.

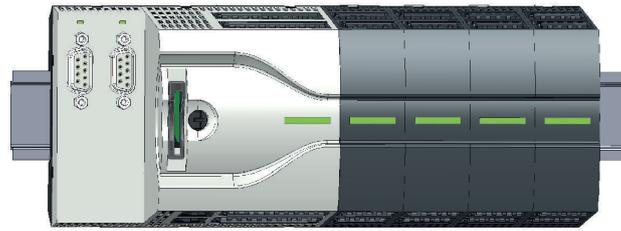


CAUTION

When working with and on electrostatic sensitive modules, make sure that personnel and equipment are adequately grounded.

2.2 System conception

Overview

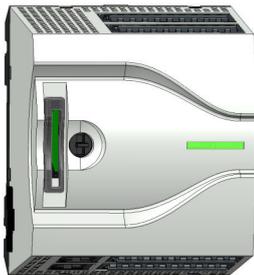


The System MICRO is a modular automation system for assembly on a 35mm profile rail. By means of periphery modules this system may be adapted matching to your automation tasks. In addition, it is possible to expand your CPU by appropriate interfaces. The wiring complexity is low, because the DC 24V electronic section supply is integrated to the backplane bus and this allows replacement with standing wire.

Components

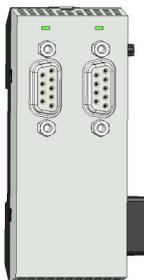
- CPU
- Extension module
- Power supply
- Periphery module

CPU



With the CPU electronic, input/output components and power supply are integrated to one casing. In addition, up to 8 periphery modules of the System MICRO can be connected to the backplane bus. As head module via the integrated power module for power supply CPU electronic and the I/O components are supplied as well as the electronic of the periphery modules, which are connected via backplane bus. To connect the power supply of the I/O components and for DC 24V electronic power supply of the periphery modules, which are connected via backplane bus, the CPU has removable connectors. By installing of up to 8 periphery modules at the backplane bus of the CPU, these are electrically connected, this means these are assigned to the backplane bus and connected to the DC 24V electronic power supply.

Extension module



By using extension modules you can extend the interfaces of the CPU. The attachment to the CPU is made by plugging on the left side of the CPU. You can only connect one extension module to the CPU at a time.

Power supply



The power supply is mounted on the left side of the profile rail with the System MICRO modules. It serves for electronics and power supply.

System conception

Periphery module



By means of up to 8 periphery modules, you can extend the internal I/O areas. The attachment to the CPU is made by plugging them on the right side of the CPU.

Profile rail



Order no.	Description
290-1AF00	35 mm profile rail length 2000mm
290-1AF30	35 mm profile rail length 530mm



NOTICE

To ensure EMC, the profile rail must be grounded!

- Ensure that the profile rail is reliably and professionally grounded.
- By mounting them on the grounded profile rail, the modules are automatically connected to the grounding system.

[‘Grounding guidelines’...page 15](#)

[‘Installation guidelines’...page 35](#)

Spare parts

The following spare parts are available for the System MICRO:

Spare part	Order no.	Description	Packaging unit
	M92-9BC00	5-fold connector for System MICRO module.	5 pieces
	M92-9BH00	10-fold connector for System MICRO CPU.	5 pieces



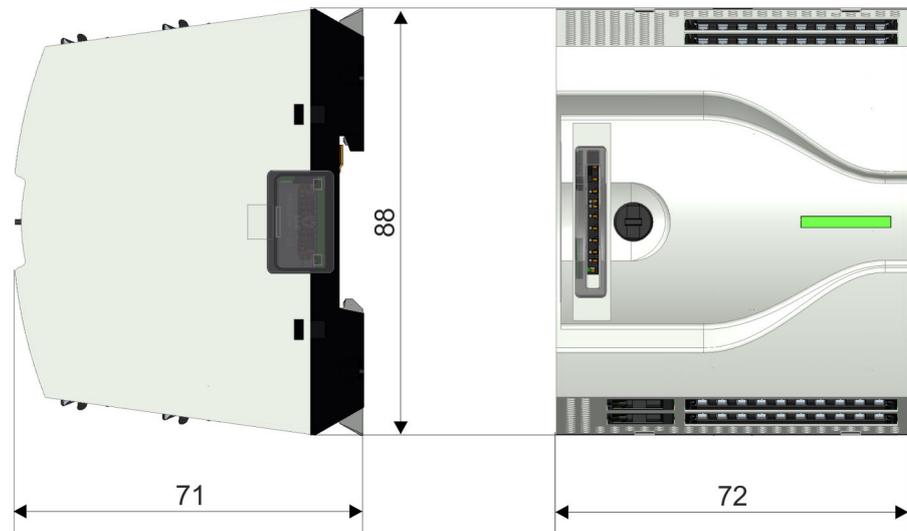
CAUTION

Please note that you may only use the spare parts with Yaskawa modules. Use with third-party modules is not allowed!

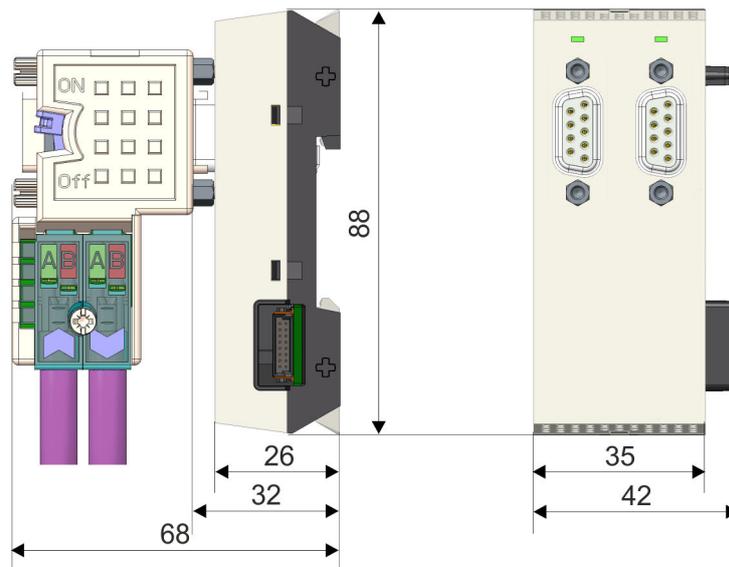
2.3 Dimensions

Dimensions CPU M13C

All dimensions are in mm.

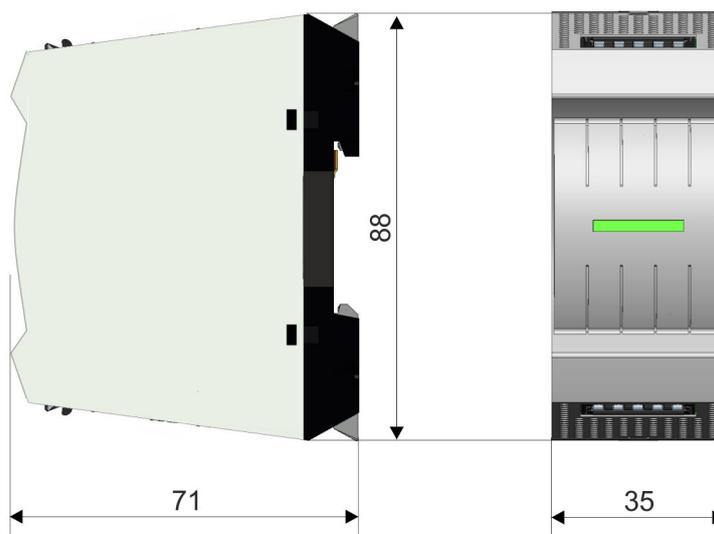


Dimensions extension module EM M09

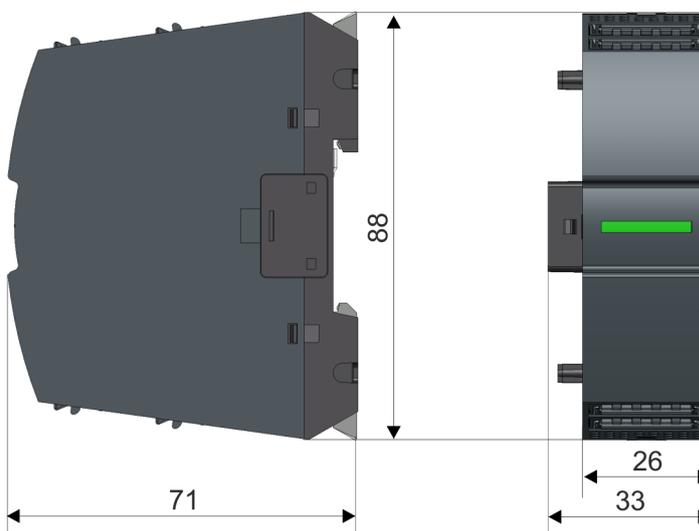


Dimensions

Dimensions power supply



Dimensions periphery module



2.4 Grounding concept

Grounding guidelines

For reliable grounding, ensure that all common ground connections and the functional earth (FE) of your System MICRO and all connected devices are connected to a central point and grounded there.



NOTICE

To ensure EMC, the profile rail must be grounded!

- Ensure that the profile rail is reliably and professionally grounded.
- By mounting them on the grounded profile rail, the modules are automatically connected to the grounding system.

'Installation guidelines'...page 35

- To avoid potential differences, use grounding cables that are as short as possible and have a large cross-section.
- When selecting grounding points, observe the applicable safety regulations.
- When assembling your components, ensure that the inactive metal parts are properly grounded over a large area.
 - Connect all inactive metal parts over a large area and with low impedance.
 - Avoid using aluminium parts if possible. Aluminium is easily oxidizing and is therefore less suitable for grounding.

2.4.1 Shielding

Overview

Shielding of the Signal lines is required for interference-free signal transmission of analog signals and counter pulses. This weakens electrical, magnetic or electromagnetic interference fields.

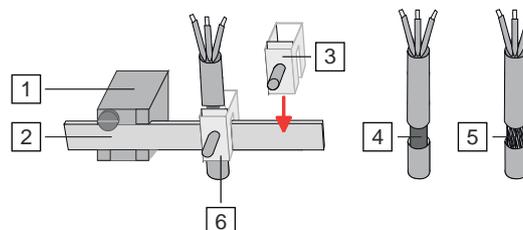
- Shielded cables must be placed directly below the module on the shield bus to be provided for this purpose.
- The shield bus must be connected locally to the base plate with low impedance.
- The shield rail must be screwed to the base plate by means of appropriate shield bus holders. Ensure a good conductive connection between the shield bus and the base plate.
- The shield bus holders are available with an internal connection for electrical contacting between the base plate and the shield bus, or in an insulated version.
- The shields of external cables must be connected to ground/earth at the control cabinet entry.

'Installation guidelines'...page 35



CAUTION

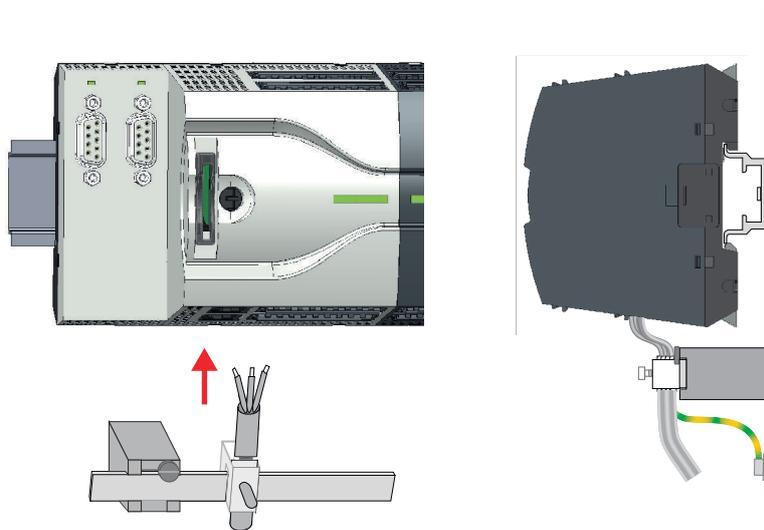
Improper shielding can lead to increased EMC radiation.



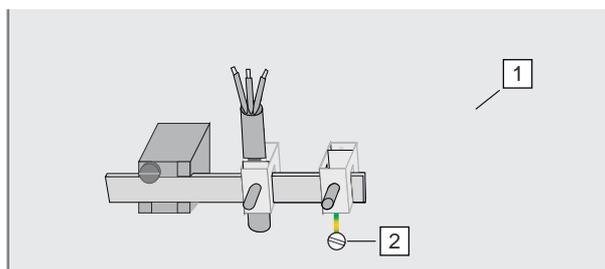
- 1 Shield bus holder
- 2 Shield bus (10mm x 3mm)
- 3 Shield clamp
- 4 Cable shield with metal foil
- 5 Cable shield with wire mesh (close-meshed)
- 6 Cable shield mounted with shield clamp

Shield attachment

1. → Mount the shield bus holders on the base plate so that the shield bus can be placed as close as possible to the System MICRO modules.
2. → Place your shield bus into the shield bus holder and fix it.



3. → Attach the cables with the accordingly stripped cable screen and fix it by the shield clamp with the shield bus.
4. → The shield bus must always be earthed. Keep all cable connections as short as possible. To earth the shield bus, connect a PE conductor to the shield bus via a shield clamp and screw it to the base plate as close as possible and with low impedance.



- 1 Base plate
- 2 PE conductor screwed to base plate

2.5 Mounting



CAUTION

Requirements for UL compliance use

- Use for power supply exclusively SELV/PELV power supplies.

2.5.1 Mounting CPU

2.5.1.1 Mounting CPU without profile rail

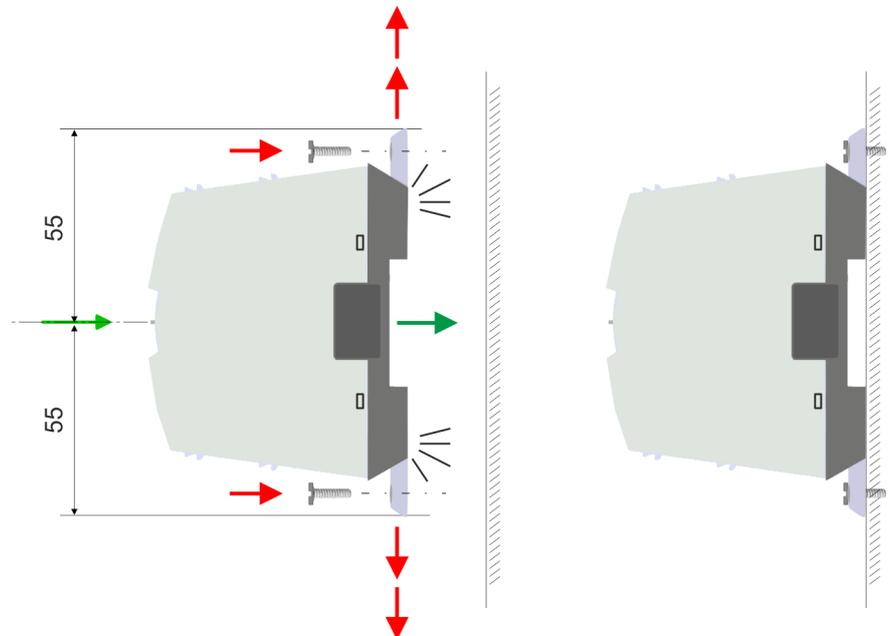


CAUTION

Mounting without profile rail is only permitted, if you only want to use the CPU without extension and periphery modules. Otherwise, a profile rail must always be used for EMC technical reasons.

Proceeding

To fulfil the EMC specifications, the System MICRO may only be operated in a metal switch cabinet with a metal base plate. You can screw the CPU to the back wall by means of screws via the locking levers. This happens with the following proceeding:



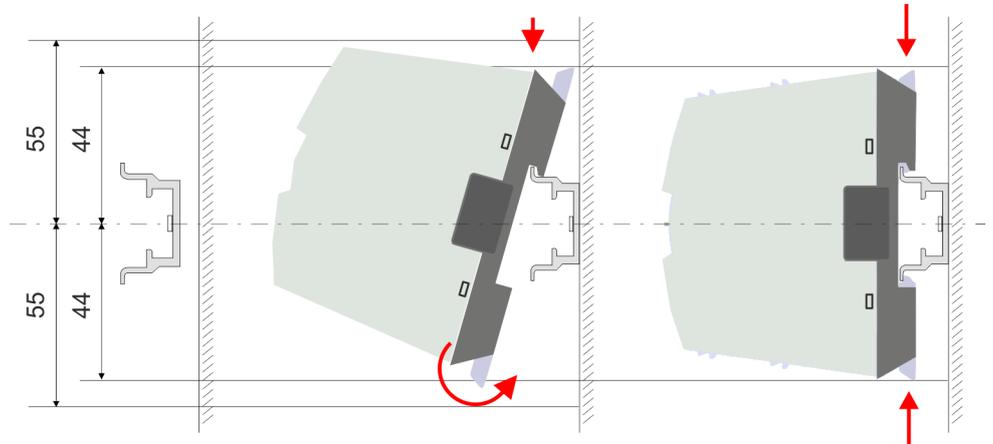
Dimensions in mm

1. The CPU has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage 2x audible.
 - ➔ By this openings on the locking levers get visible.
2. Use the appropriate screws to fix your CPU to your back wall. Consider the installation clearances for the CPU.
 - ➔ The CPU is now mounted and can be wired.

2.5.1.2 Mounting with profile rail

Proceeding

To fulfil the EMC specifications, the System MICRO may only be operated in a metal switch cabinet with a metal base plate.



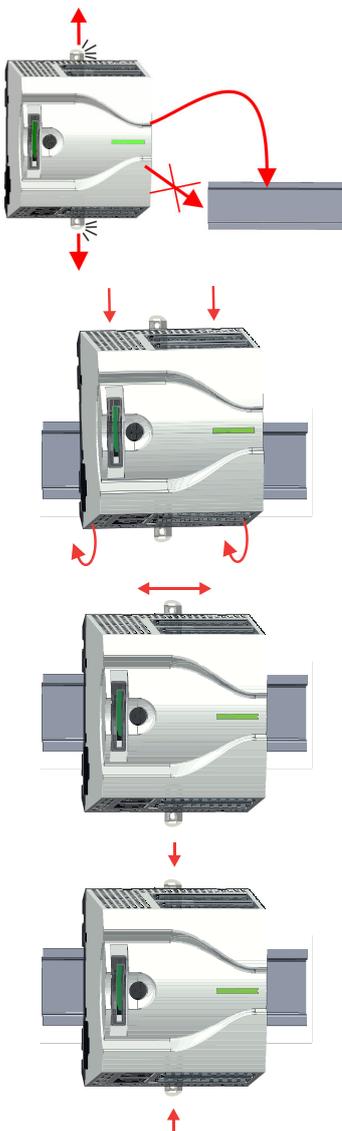
Dimensions in mm

1. → Mount the profile rail. Please consider that a clearance from the middle of the profile rail of at least 44mm respectively 55mm above and below exists.
2. → The CPU has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.



CAUTION

It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged.



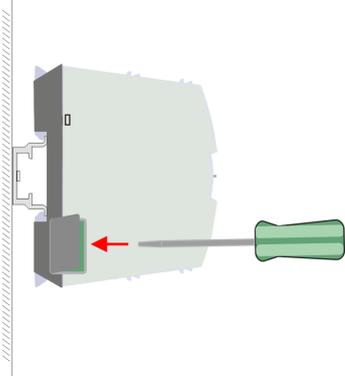
3. → Plug the CPU from the top onto the profile rail and turn the CPU downward until it rests on the profile rail.
4. → Move the CPU on the profile rail at its position.
5. → To fix the CPU at the profile rail, move the locking levers back to the initial position.
 - The CPU is now mounted and can be wired.

2.5.2 Mounting the extension module

Proceeding

You have the possibility to extend the interfaces of the CPU by plugging an extension module. For this the extension module is plugged at the left side of the CPU. The mountings happens with the following proceeding:

1. → Remove the bus cover with a screwdriver on the left side of the CPU.



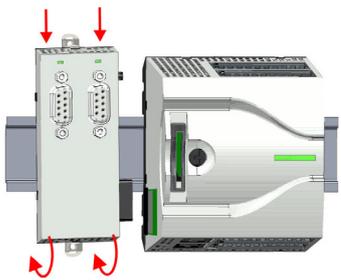
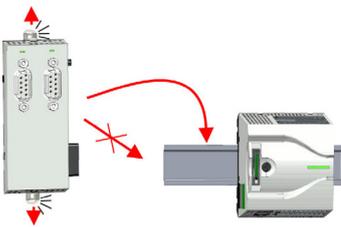
2. → The extension module has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.



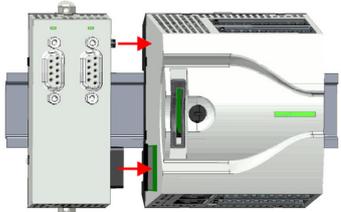
CAUTION

It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged.

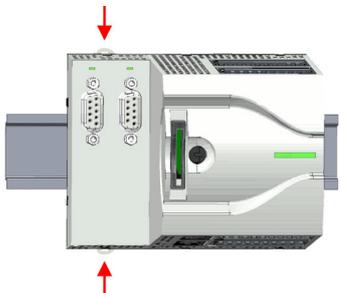
3. → To mount plug the extension module from the top onto the profile rail and turn the extension module downward until it rests on the profile rail.



4. → Attach the extension module to the CPU by sliding the extension module on the profile rail to the right until the interface connector slightly locks into the CPU.



5. → To fix the extension module at the profile rail, move the locking levers back to the initial position.

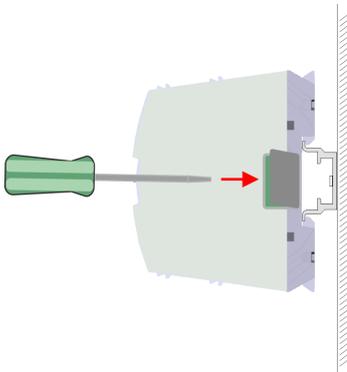


2.5.3 Mounting periphery module

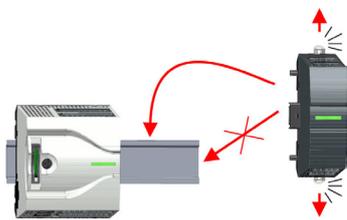
Proceeding

You have the possibility to extend the periphery area of the CPU by plugging up to 8 periphery modules. For this the periphery modules are plugged at the right side of the CPU. The mountings happens with the following proceeding:

1. → Remove the bus cover with a screwdriver on the right side of the CPU.



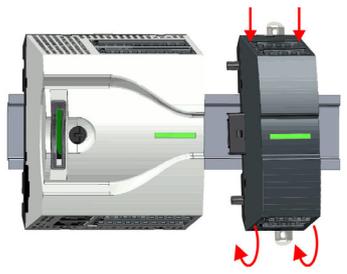
2. → Each periphery module has a locking lever on its upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.



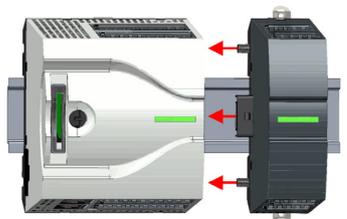
CAUTION

It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged.

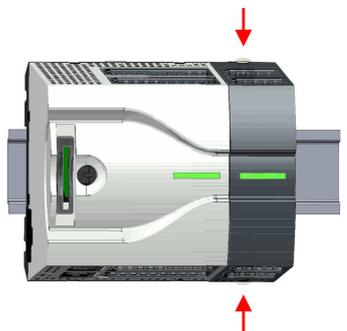
3. → To mount plug the periphery module from the top onto the profile rail and turn the periphery module downward until it rests on the profile rail.



4. → Attach the periphery module to the CPU by sliding the periphery module on the profile rail to the left until the interface connector slightly locks into the CPU.



5. → To fix the periphery module at the profile rail, move the locking levers back to the initial position.



6. → Proceed in this way with additional periphery modules.

2.6 Wiring

Notes and guidelines



DANGER

Consider strain relief of the supply lines!

Since the plug for the supply lines of the input voltage has no (double) insulation, not permanently fixed supply lines must be relieved from push and pull!



CAUTION

Consider temperature for external cables!

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!



CAUTION

Separate insulation areas!

The system is specified for SELV/PELV environment. Devices, which are attached to the system must meet these specifications. Installation and cable routing other than SELV/PELV specification must be separated from the system's equipment!

2.6.1 Wiring CPU

CPU connector

For wiring the CPU has removable connectors. With the wiring of the connectors a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver with 2.5mm blade width.

Data



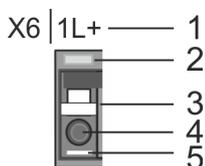
Please use copper wire only!

U_{max}	30V DC
I_{max}	10A
Cross section	0.2 ... 1.5mm ² (AWG 24 ... 16)
Stripping length	10mm

Shield attachment

[‘Shielding’...page 15](#)

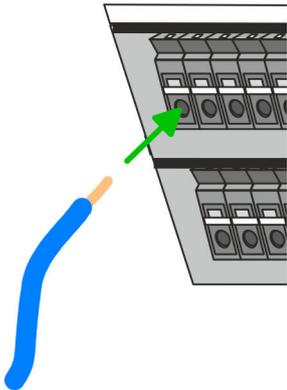
Wiring procedure



→ Determine according to the casing labelling the connection position.

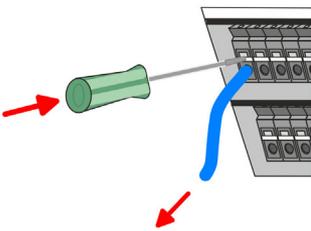
- 1 Labeling on the casing
- 2 Status LED
- 3 Release area
- 4 Connection hole for wire
- 5 Pin 1 of the connector is labelled by a white line

Insert wire



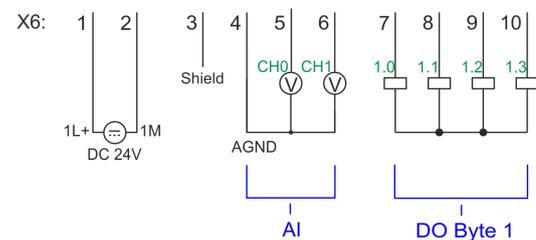
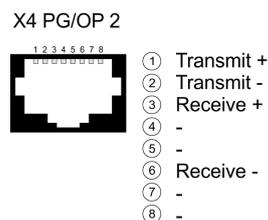
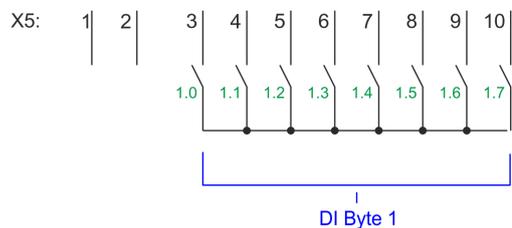
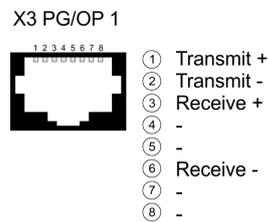
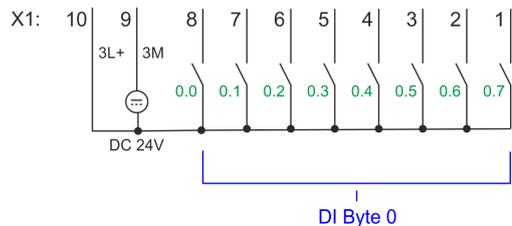
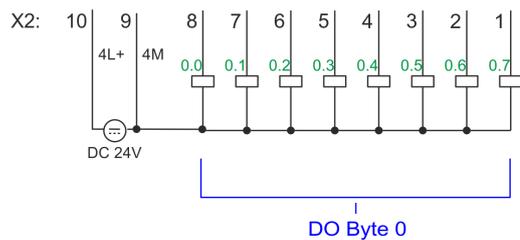
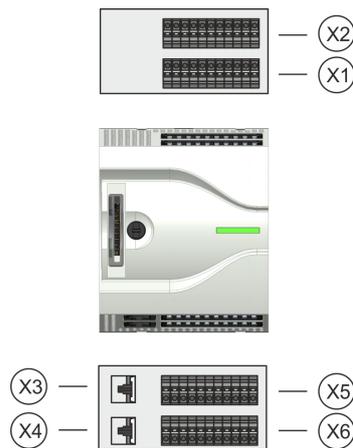
- ➔ Insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed. When using stranded wires you have to press the release button with the screwdriver during the wiring.
- ➔ By pushing the contact spring opens, thus ensuring the necessary contact pressure.

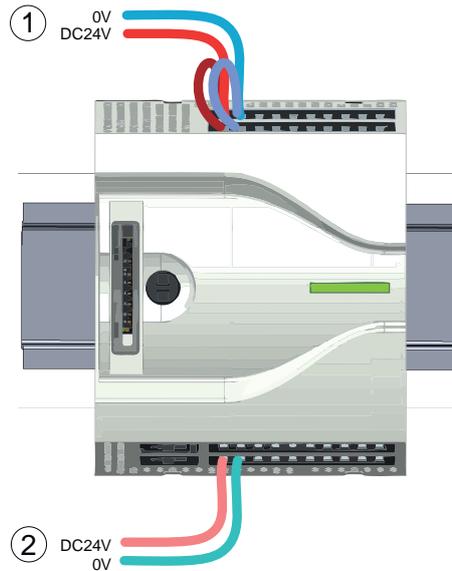
Remove wire



1. ➔ The wire is to be removed by means of the screwdriver. Press with your screwdriver vertically at the release button.
 - ➔ The contact spring releases the wire.
2. ➔ Pull the wire from the round hole.

Standard wiring





- (1) X2: 4L+: DC 24V power section supply for integrated outputs
X1: 3L+: DC 24V power section supply for integrated inputs
- (2) X6: 1L+ DC 24V for electronic power supply



The electronic power section supply is internally protected against higher voltage by fuse. The fuse is located inside the CPU and can not be changed by the user.

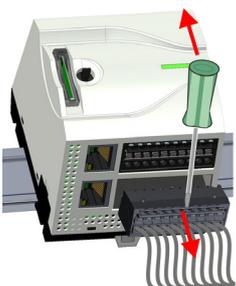
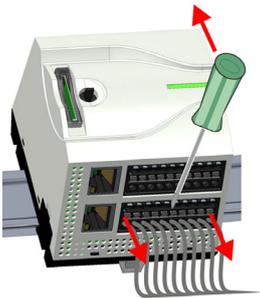
Fusing



CAUTION

- The power section supply of the internal DOs is to be externally protected with a 8A fuse (fast) respectively by a line circuit breaker 8A characteristics Z.

Remove connector



By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

1. Remove connector:

Insert your screwdriver from above into one of the indentations.

2. Push the screwdriver backwards:

➔ The connector is unlocked and can be removed.



CAUTION

Via wrong operation such as pressing the screwdriver downward, the release lever may be damaged.

3. Plug connector:

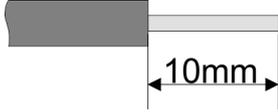
The connector is plugged by plugging it directly into the release lever.

2.6.2 Wiring periphery module

Periphery module connector

For wiring the periphery module has removable connectors. With the wiring of the connectors a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver with 2.5mm blade width.

Data



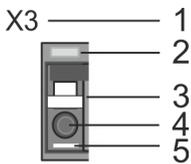
Please use copper wire only!

U_{max}	240V AC / 30V DC
I_{max}	10A
Cross section	0.2 ... 1.5mm ² (AWG 24 ... 16)
Stripping length	10mm

Shield attachment

[‘Shielding’...page 15](#)

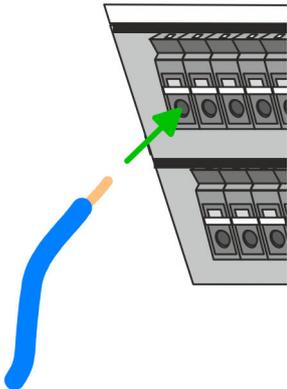
Wiring procedure



→ Determine according to the casing labelling the connection position.

- 1 Labeling on the casing
- 2 Status LED
- 3 Release area
- 4 Connection hole for wire
- 5 Pin 1 of the connector is labelled by a white line

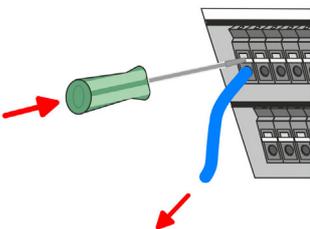
Insert wire



→ Insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed. When using stranded wires you have to press the release button with the screwdriver during the wiring.

- ➔ By pushing the contact spring opens, thus ensuring the necessary contact pressure.

Remove wire



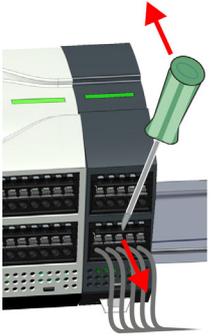
1. → The wire is to be removed by means of the screwdriver. Press with your screwdriver vertically at the release button.
 - ➔ The contact spring releases the wire.
2. → Pull the wire from the round hole.

Fusing



CAUTION

- The power section supply of the output modules DO16 is to be externally protected with a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z.
- The power section supply of the output part of the DIO8 is to be externally protected with a 5A fuse (fast) respectively by a line circuit breaker 5A characteristics Z.

Remove connector

By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

1. → Remove connector:

Insert your screwdriver from above into one of the indentations.

2. → Push the screwdriver backwards:

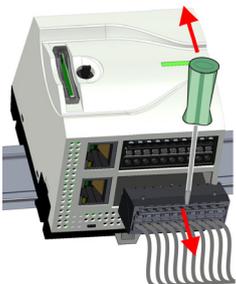
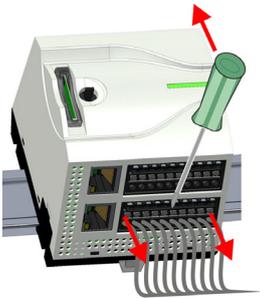
→ The connector is unlocked and can be removed.

**CAUTION**

Via wrong operation such as pressing the screwdriver downward, the release lever may be damaged.

3. → Plug connector:

The connector is plugged by plugging it directly into the release lever.

2.7 Demounting**2.7.1 Demounting CPU****Remove connector**

By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

1. → Power-off your system.

2. → Remove connector:

Insert your screwdriver from above into one of the indentations.

3. → Push the screwdriver backwards:

→ The connector is unlocked and can be removed.

**CAUTION**

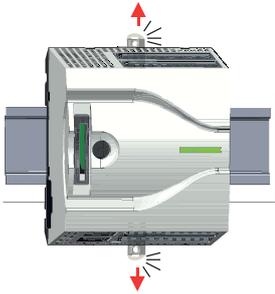
Via wrong operation such as pressing the screwdriver downward, the connector may be damaged!

4. → In this way, remove all plugged connectors on the CPU.

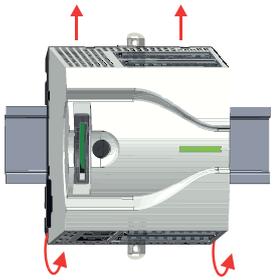
CPU replacement (stand-alone)

If more modules are connected to the CPU '*Option: CPU replacement in a system*'...page 27. If no other modules are connected to the CPU, the CPU is replaced according to the following proceeding:

1. Use a screwdriver to pull the locking levers of the CPU outwards until these engage audible.



2. Remove the CPU with a rotation upwards from the profile rail.

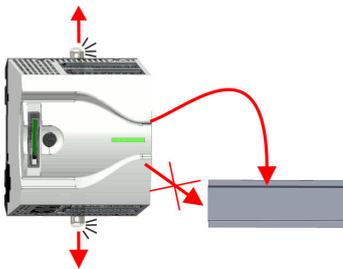


3. Pull the locking levers of the CPU outwards until these engage audible.

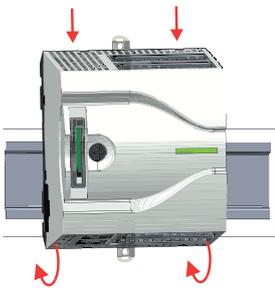


CAUTION

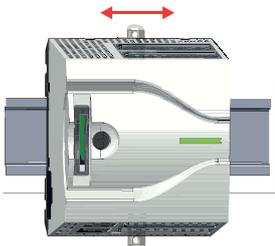
It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged!



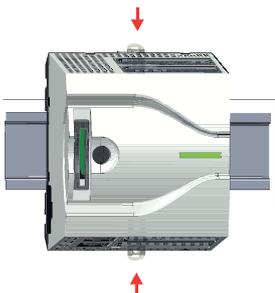
4. Plug the CPU from the top onto the profile rail and turn the CPU downward until it rests on the profile rail.

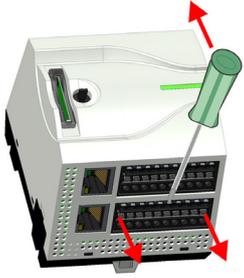


5. Move the CPU on the profile rail at its position.

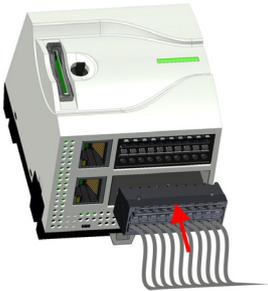


6. To fix the CPU at the profile rail, move the locking levers back to the initial position.





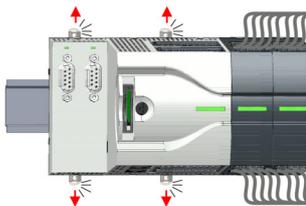
7. → Remove the connectors, which are not necessary at the CPU.



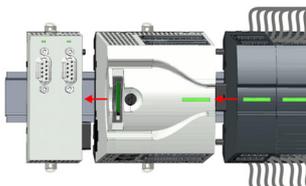
8. → Plug again the wired connectors.
 ➔ Now you can bring your system back into operation.

Option: CPU replacement in a system

In the following the replacement of a CPU in a system is shown:



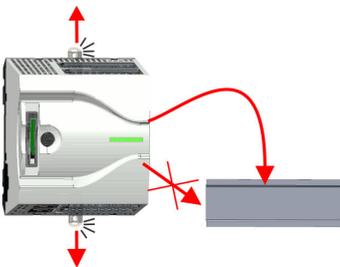
1. → If there is an extension module connected to the CPU, you have to remove it from the CPU. For this use a screwdriver to pull the locking levers of the extension module and CPU outwards until these engage audible.



2. → Disconnect all the modules, which are connected to the CPU by moving the CPU along with the extension module on the profile rail.



3. → Remove the CPU with a rotation upwards from the profile rail.



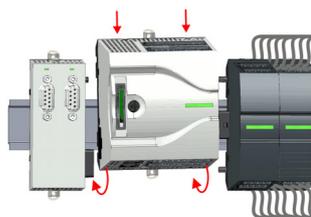
4. → Pull the locking levers of the CPU outwards until these engage audible.



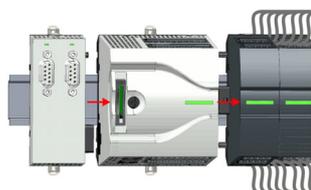
CAUTION

It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged!

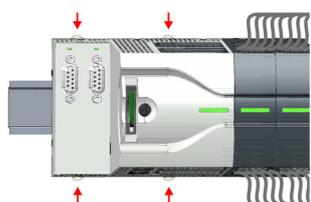
Demounting > Demounting CPU



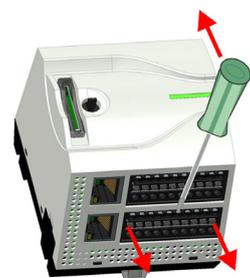
5. → For mounting pull the locking levers of the CPU outwards until these engage audible. Plug the CPU from the top onto the profile rail and turn the CPU downward until it rests on the profile rail.



6. → Rebind your modules by moving the CPU along with the extension module on the profile rail.



7. → To fix the CPU at the profile rail, move the locking levers back to the initial position.



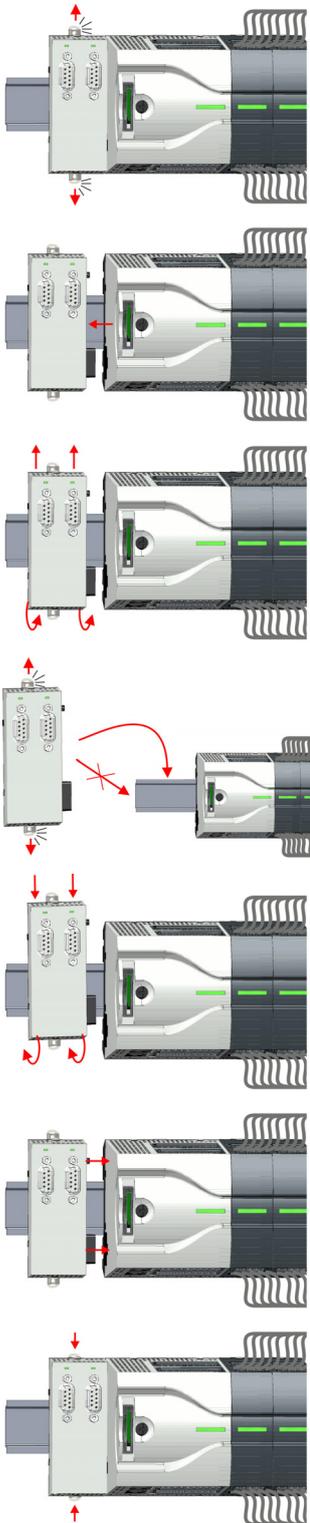
8. → Remove the connectors, which are not necessary at the CPU.



9. → Plug again the wired connectors.
 → Now you can bring your system back into operation.

2.7.2 Demounting the extension module

Proceeding



1. ➤ Power-off your system.
2. ➤ Remove the corresponding bus connectors.
3. ➤ Use a screwdriver to pull the locking levers of the extension module outwards until these engage audible.

4. ➤ Remove the extension module from the CPU by sliding it on the profile rail.

5. ➤ Remove the extension module with a rotation upwards from the profile rail.

6. ➤ Pull the locking levers of the extension module outwards until these engage audible.



CAUTION

It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged!

7. ➤ Plug the extension module from the top onto the profile rail and turn the extension module downward until it rests on the profile rail.

8. ➤ Reattach the extension module to the CPU by sliding the extension module on the profile rail to the right until the interface connector slightly locks into the CPU.

9. ➤ Move the locking levers back to the initial position.

10. ➤ Plug the corresponding bus connectors.

➔ Now you can bring your system back into operation.

2.7.3 Demounting periphery module

Remove connector

By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

1. → Power-off your system.

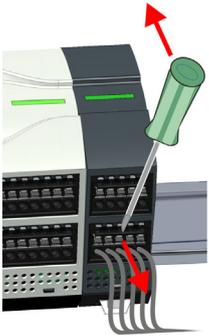


CAUTION

Make sure that the working contacts from the relay module are disconnected from the power supply!

2. → Remove connector:

Insert your screwdriver from above into one of the indentations.



3. → Push the screwdriver backwards:

→ The connector is unlocked and can be removed.



CAUTION

Via wrong operation such as pressing the screwdriver downward, the connector may be damaged!

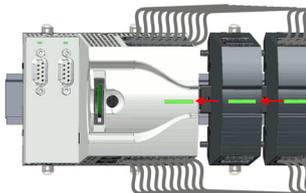


4. → In this way, remove all plugged connectors on the periphery module.

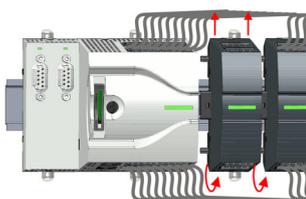
Replace the periphery module



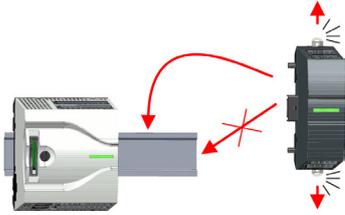
1. → Remove the modules that are connected to the module to be replaced by pulling their release levers outwards until these engage audible ...



2. → ... and move the modules accordingly.



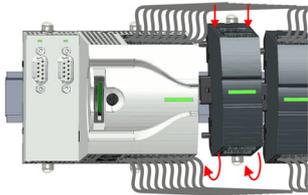
3. → Remove the periphery module with a rotation upwards from the profile rail.



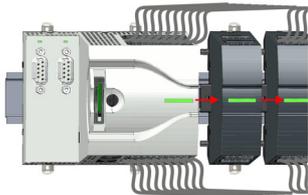
4. → Pull the locking levers outwards until these engage audible.

**CAUTION**

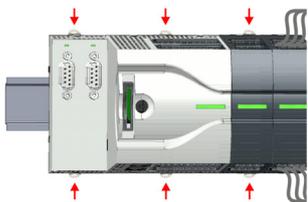
It is not allowed to mount the module sideways on the profile rail, as otherwise the module may be damaged!



5. → Plug the periphery module from the top onto the profile rail and turn the periphery module downward until it rests on the profile rail.



6. → Reconnect all modules by pushing them together again on the profile rail.



7. → Move the locking levers back to the initial position.



8. → Remove the connectors, which are not necessary.



9. → Plug again the wired connectors.
 ➔ Now you can bring your system back into operation.

2.7.3.1 Easy Maintenance

Overview

Easy Maintenance means the support for adding and removing modules during operation without having to restart the system. There are the following behaviors:

- Periphery module is removed
 - The CPU detects a module failure on the backplane bus.
 - Diagnostic message ‘*System MICRO bus failure*’ (0x39D0) is triggered.
 - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
 - The red LED of the status bar of the CPU lights up.
 - The I/O data of all modules become invalid.
- Identical periphery module is plugged
 - The CPU detects the module return on the backplane bus.
 - The red LED of the status bar of the CPU gets off.
 - All green LEDs of the status bars of the peripheral modules get on and all the red LEDs of the status bars of the peripheral modules get off.
 - Diagnostic message ‘*System MICRO bus recovery*’ (0x38D0) is triggered.
 - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
 - The I/O data of all modules become valid again.
- Wrong periphery module is plugged
 - The CPU detects the wrong module.
 - Diagnostic message ‘*System MICRO bus recovery, but expected configuration does not match actual configuration*’ (0x38D1) is triggered.
 - The red LED of the status bar of the CPU remains on.
 - The red LED of the status bar of the wrong I/O module flashes.
 - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
 - With the exception of the wrong module, the I/O data of all modules become valid again.



Please note that the CPU switches to STOP, if there is no OB 86 configured when adding or removing System MICRO modules!

2.8 Industrial security and installation guidelines

2.8.1 Industrial security in information technology

Latest version

This chapter can also be found as a guide *'Industrial IT Security'* in the *'Download Center'* of www.yaskawa.eu.com

Hazards

The topic of data security and access protection has become increasingly important in the industrial environment. The increased networking of entire industrial systems to the network levels within the company together with the functions of remote maintenance have all served to increase vulnerability. Hazards can arise from:

- Internal manipulation such as technical errors, operating and program errors and deliberate program or data manipulation.
- External manipulation such as software viruses, worms and trojans.
- Human carelessness such as password phishing.

Precautions

The most important precautions to prevent manipulation and loss of data security in the industrial environment are:

- Encrypting the data traffic by means of certificates.
- Filtering and inspection of the traffic by means of VPN - "Virtual Private Networks".
- Identification of the user by "Authentication" via safe channels.
- Segmenting in protected automation cells, so that only devices in the same group can exchange data.
- Deactivation of unnecessary hardware and software.

Further Information

You can find more information about the measures on the following websites:

- Federal Office for Information Technology → www.bsi.bund.de
- Cybersecurity & Infrastructure Security Agency → us-cert.cisa.gov
- VDI / VDE Society for Measurement and Automation Technology → www.vdi.de

2.8.1.1 Protection of hardware and applications

Precautions

- Do not integrate any components or systems into public networks.
 - Use VPN "Virtual Private Networks" for use in public networks. This allows you to control and filter the data traffic accordingly.
- Always keep your system up-to-date.
 - Always use the latest firmware version for all devices.
 - Update your user software regularly.
- Protect your systems with a firewall.
 - The firewall protects your infrastructure internally and externally.
 - This allows you to segment your network and isolate entire areas.
- Secure access to your plants via user accounts.
 - If possible, use a central user management system.
 - Create a user account for each user for whom authorization is essential.
 - Always keep user accounts up-to-date and deactivate unused user accounts.
- Secure access to your plants via secure passwords.
 - Change the password of a standard login after the first start.
 - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
 - Change the passwords according to the rules and guidelines that apply to your application.
- Deactivate inactive communication ports respectively protocols.
 - Only the communication ports that are used for communication should be activated.
 - Only the communication protocols that are used for communication should be activated.
- Consider possible defence strategies when planning and securing the system.
 - The isolation of components alone is not sufficient for comprehensive protection. An overall concept is to be drawn up here, which also provides defensive measures in the event of a cyber attack.
 - Periodically carry out threat assessments. Among others, a comparison is made here between the protective measures taken and those required.
- Limit the use of external storage media.
 - Via external storage media such as USB memory sticks or SD memory cards, malware can get directly into a system while bypassing a firewall.
 - External storage media or their slots must be protected against unauthorized physical access, e.g. by using a lockable control cabinet.
 - Make sure that only authorized persons have access.
 - When disposing of storage media, make sure that they are safely destroyed.
- Use secure access paths such as HTTPS or VPN for remote access to your plant.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.

2.8.1.2 Protection of PC-based software

Precautions

Since PC-based software is used for programming, configuration and monitoring, it can also be used to manipulate entire systems or individual components. Particular caution is required here!

- Use user accounts on your PC systems.
 - If possible, use a central user management system.
 - Create a user account for each user for whom authorization is essential.
 - Always keep user accounts up-to-date and deactivate unused user accounts.
- Protect your PC systems with secure passwords.
 - Change the password of a standard login after the first start.
 - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
 - Change the passwords according to the rules and guidelines that apply to your application.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.
- Protect your PC systems by security software.
 - Install virus scanners on your PC systems to identify viruses, trojans and other malware.
 - Install software that can detect phishing attacks and actively prevent them.
- Always keep your software up-to-date.
 - Update your operating system regularly.
 - Update your software regularly.
- Make regular backups and store the media at a safe place.
- Regularly restart your PC systems. Only boot from storage media that are protected against manipulation.
- Use encryption systems on your storage media.
- Perform security assessments regularly to reduce the risk of manipulation.
- Use only data and software from approved sources.
- Uninstall software which is not used.
- Disable unused services.
- Activate a password-protected screen lock on your PC systems.
- Always lock your PC systems as soon as you leave your PC workstation.
- Do not click any links that come from unknown sources. If necessary ask, e.g. on e-mails.
- Use secure access paths such as HTTPS or VPN for remote access to your PC system.

2.8.2 Installation guidelines

General

The installation guidelines contain information about the interference free deployment of a PLC system. There is the description of the ways, interference may occur in your PLC, how you can make sure the electromagnetic compatibility (EMC), and how you manage the isolation.

What does EMC mean?

Electromagnetic compatibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interfered respectively without interfering the environment.

The components are developed for the deployment in industrial environments and meets high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

Possible interference causes

Electromagnetic interferences may interfere your control via different ways:

- Electromagnetic fields (RF coupling)
- Magnetic fields with power frequency
- Bus system
- Power supply
- Protected ground conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

There are:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

Basic rules for EMC

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
 - Connect all inactive metal extensive and impedance-low.
 - Please try not to use aluminium parts. Aluminium is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
 - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
 - Always lay your high voltage lines and signal respectively data lines in separate channels or bundles.
 - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).
- Proof the correct fixing of the lead isolation.
 - Data lines must be shielded.
 - Analog lines must be shielded. When transmitting signals with small amplitudes the one sided laying of the isolation may be favourable.
 - Cables for frequency inverters, servo and stepper motors must be shielded.
 - Lay the line isolation extensively on an isolation/protected ground conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
 - Make sure that the isolation/protected ground conductor rail is connected impedance-low with the cabinet.
 - Use metallic or metallised plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
 - Consider to wire all inductivities with erase links.
 - Please consider luminescent lamps can influence signal lines.
- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
 - Please take care for the targeted employment of the grounding actions. The grounding of the PLC serves for protection and functionality activity.
 - Connect installation parts and cabinets with your PLC in star topology with the isolation/protected ground conductor system. So you avoid ground loops.
 - If there are potential differences between installation parts and cabinets, lay sufficiently dimensioned potential compensation lines.

Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption. Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Here you have to make sure, that the connection to the protected ground conductor is impedance-low, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area. Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
 - the conduction of a potential compensating line is not possible.
 - analog signals (some mV respectively μA) are transferred.
 - foil isolations (static isolations) are used.
- With data lines always use metallic or metallised plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected ground conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet.

**CAUTION****Please regard at installation!**

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

Remedy: Potential compensation line

2.9 General data for the System MICRO**Conformity and approval**

Conformity

CE	2014/35/EU	Low Voltage Directive
	2014/30/EU	EMC Directive
RoHS (EU)	2011/65/EU	Restriction of the use of certain hazardous substances in electrical and electronic equipment
UKCA	2016 No. 1101	Electrical Equipment (Safety) Regulations
	2016 No. 1091	Electromagnetic Compatibility Regulations
RoHS (UK)	2012 No. 3032	Use of Certain Hazardous Substances

Approval

UL	-	Refer to Technical data
----	---	-------------------------

General data for the System MICRO

Protection of persons and device protection		
Type of protection	-	IP20
Electrical isolation		
to the field bus	-	electrically isolated
to the process level	-	electrically isolated
Insulation resistance	-	-
Insulation voltage to reference earth		
Inputs / outputs	-	AC / DC 50V, test voltage AC 500V
Protective measures	-	against short circuit

Environmental conditions to EN 61131-2		
Climatic		
Storage / transport	EN 60068-2-14	-25...+70°C
Operation		
Horizontal installation hanging	EN 61131-2	0...+60°C
Horizontal installation lying	EN 61131-2	0...+60°C
Vertical installation	EN 61131-2	0...+60°C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10...95%)
Pollution	EN 61131-2	Degree of pollution 2
Installation altitude max.	-	2000m
Mechanical		
Oscillation	EN 60068-2-6	1g, 9Hz ... 150Hz
Shock	EN 60068-2-27	15g, 11ms

Mounting conditions		
Mounting place	-	In the control cabinet
Mounting position	-	Horizontal and vertical

EMC	Standard	Comment
Emitted interference	EN 61000-6-4	Class A (Industrial area)
Noise immunity zone B	EN 61000-6-2	Industrial area
		EN 61000-4-2
	EN 61000-4-3	HF field immunity (casing) 80MHz ... 1000MHz, 10V/m, 80% AM (1kHz) 1.4GHz ... 2.0GHz, 3V/m, 80% AM (1kHz) 2GHz ... 2.7GHz, 1V/m, 80% AM (1kHz)

EMC	Standard	Comment
	EN 61000-4-6	HF conducted 150kHz ... 80MHz, 10V, 80% AM (1kHz)
	EN 61000-4-4	Burst
	EN 61000-4-5	Surge ¹

1) Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

2.9.1 Use in difficult operating conditions



Without additional protective measures, the products must not be used in locations with difficult operating conditions; e.g. due to:

- dust generation
- chemically active substances (corrosive vapors or gases)
- strong electric or magnetic fields

3 Analog input

3.1 General

Cables for analog signals

For analog signals you should use screened cables to reduce interference. The cable screening should be grounded at both ends. If there are differences in the potential between the cable ends, there may occur a potential compensating current that could disturb the analog signals. In this case you should ground the cable screening only at one end.

Connecting sensors

Depending on the module the following sensors may be connected to the analog input modules:

- Current sensor
- Voltage sensor
- Resistance-type sensors
- Temperature sensors



*Please take care of the correct polarity when installing the sensors!
Please install short circuits at non-used inputs by connecting the positive contact with the channel ground of the according channel.*

Parameterization

The parameterization via CPU, PROFIBUS and PROFINET happens by means of record sets (DS). The corresponding record set number may be found at the respective module description.

Diagnostic functions

The modules have diagnostics capability. The following errors can release a diagnostic:

- Error in parameterization
- Measuring range over-/underflow
- Wire break



Alternated blinking of the channel error LEDs

The alternate blinking of the channel error LEDs of channel 0 and 1 indicates a watchdog error due to a system overload. Restart with a power cycle your system. If the error occurred again, check configuration and circuit and adjust them if necessary. If the error persists, please contact our support.

3.2 Analog value

Representation of analog values

Analog values are exclusively processed in a binary format. For this the analog module transforms every process signal into a digital value and transfers this as word. The analog values are displayed as a fixed-point number in the two's complement.

Resolu- tion	Analog value															
	High byte (byte 0)								Low byte (byte 1)							
Bit number	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Value	SG	2^{14}	2^{13}	2^{12}	2^{11}	2^{10}	2^9	2^8	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0
16bit	SG	Measuring value														

Sign bit (SG)

Here it is essential:

- Bit 15 = "0": → positive value
- Bit 15 = "1": → negative value

Behavior at error

As soon as a measured value exceeds the overdrive region respectively falls below the underdrive region, the following value is issued:

- Measuring value > end of overdrive region:
32767 (7FFFh)
- Measuring value < end of underdrive region:
-32768 (8000h)

At a parameterization error the value 32767 (7FFFh) is issued.

3.3 Measuring ranges and function numbers

General

In the following there are the measuring ranges with function number listed, which were supported by the corresponding analog module. The here listed formulas allow you to transform an evaluated measuring value (analog value) to a value assigned to the measuring range (digital value) and vice versa.

Voltage

0 ... 10V

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
0 ... 10V Siemens S7 format (10h)	11.76V	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{27648}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	-1.76V	-4864	ED00h	underrange	
0 ... 10V Siemens S5 format (20h)	12.5V	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{16384}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	-2V	-3277	F333h	underrange	

Voltage

±10V

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V Siemens S7 format (12h)	11.76V	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{27648}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	-5V	-13824	CA00h		
	-10V	-27648	9400h		
	-11.76V	-32512	8100h	underrange	
±10V Siemens S5 format (22h)	12.5V	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{16384}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	-5V	-8192	E000h		
	-10V	-16384	C000h		
	-12.5V	-20480	B000h	underrange	

Voltage

-80 ... 80mV

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
-80 ... 80mV	94.07mV	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{80}$
Siemens S7 format (11h)	80mV	27648	6C00h	nominal range	
	0V	0	0000h		
	-80mV	-27648	9400h	underrange	
	-94.07mV	-32512	8100h		
-80 ... 80mV	100mV	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{80}$
Siemens S5 format (21h)	80mV	16384	4000h	nominal range	
	0V	0	0000h		
	-80mV	-16384	C000h	underrange	
	-100mV	-20480	B000h		
					$U = D \cdot \frac{80}{27648}$
					$U = D \cdot \frac{80}{16384}$

Current

0(4) ... 20mA

Meas. range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
0 ... 20mA	23.52mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I}{20}$
Siemens S7 format (31h)	20mA	27648	6C00h	nominal range	
	10mA	13824	3600h		
	0mA	0	0000h	underrange	
	-3.52mA	-4864	ED00h		
0 ... 20mA	25.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I}{20}$
Siemens S5 format (41h)	20mA	16384	4000h	nominal range	
	10mA	8192	2000h		
	0mA	0	0000h	underrange	
	-4,00mA	-3277	F333h		
4 ... 20mA	22.81mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I-4}{16}$
Siemens S7 format (30h)	20mA	27648	6C00h	nominal range	
	12mA	13824	3600h		
	4mA	0	0000h	underrange	
	1.19mA	-4864	ED00h		
4 ... 20mA	24.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I-4}{16}$
Siemens S5 format (40h)	20mA	16384	4000h	nominal range	
	12mA	8192	2000h		
	4mA	0	0000h	underrange	
	0.8mA	-3277	F333h		
					$I = D \cdot \frac{20}{27648}$
					$I = D \cdot \frac{20}{16384}$
					$I = D \cdot \frac{16}{27648} + 4$
					$I = D \cdot \frac{16}{16384} + 4$

Measuring ranges and function numbers

RTD

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: PT100 (50h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
2 wire: PT1000 (51h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
2 wire: NI100 (52h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
2 wire: NI1000 (53h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
3 wire: PT100 (58h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
3 wire: PT1000 (59h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
3 wire: NI100 (5Ah)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
3 wire: NI1000 (5Bh)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
4 wire: PT100 (60h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
4 wire: PT1000 (61h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
4 wire: NI100 (62h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
4 wire: NI1000 (63h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: 0 ... 60Ω (70h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 600Ω (71h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 3000Ω (72h)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 60Ω (78h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 600Ω (79h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 3000Ω (7Ah)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 60Ω (80h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 600Ω (81h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 3000Ω (82h)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 60Ω (90h)	---	---	overrange
	0 ... 60Ω	0 ... 6000	nominal range
	---	---	underrange
2 wire: 0 ... 600Ω (91h)	---	---	overrange
	0 ... 600Ω	0 ... 6000	nominal range
	---	---	underrange
2 wire: 0 ... 3000Ω (92h)	---	---	overrange
	0 ... 3000Ω	0 ... 30000	nominal range
	---	---	underrange
3 wire: 0 ... 60Ω	---	---	overrange

Measuring ranges and function numbers

Measuring range (funct. no.)	Measuring value	Signal range	Range
(98h)	0 ... 60Ω	0 ... 6000	nominal range
	---	---	underrange
3 wire: 0 ... 600Ω (99h)	---	---	overrange
	0 ... 600Ω	0 ... 6000	nominal range
3 wire: 0 ... 3000Ω (9Ah)	---	---	underrange
	0 ... 3000Ω	0 ... 30000	nominal range
4 wire: 0 ... 60Ω (A0h)	---	---	overrange
	0 ... 60Ω	0 ... 6000	nominal range
4 wire: 0 ... 600Ω (A1h)	---	---	underrange
	0 ... 600Ω	0 ... 6000	nominal range
4 wire: 0 ... 3000Ω (A2h)	---	---	overrange
	0 ... 3000Ω	0 ... 30000	nominal range
2 wire: 0 ... 60Ω (D0h)	---	---	underrange
	70.55Ω	32511	overrange
2 wire: 0 ... 600Ω (D1h)	0 ... 60Ω	0 ... 27648	nominal range
	---	---	underrange
2 wire: 0 ... 3000Ω (D2h)	705.5Ω	32511	overrange
	0 ... 600Ω	0 ... 27648	nominal range
2 wire: 0 ... 3000Ω (D2h)	---	---	underrange
	3528Ω	32511	overrange
3 wire: 0 ... 60Ω (D8h)	0 ... 3000Ω	0 ... 27648	nominal range
	---	---	underrange
3 wire: 0 ... 600Ω (D9h)	70.55Ω	32511	overrange
	0 ... 60Ω	0 ... 27648	nominal range
3 wire: 0 ... 600Ω (D9h)	---	---	underrange
	705.5Ω	32511	overrange
3 wire: 0 ... 3000Ω (DAh)	0 ... 600Ω	0 ... 27648	nominal range
	---	---	underrange
4 wire: 0 ... 60Ω (E0h)	3528Ω	32511	overrange
	0 ... 3000Ω	0 ... 27648	nominal range
4 wire: 0 ... 60Ω (E0h)	---	---	underrange
	70.55Ω	32511	overrange
4 wire: 0 ... 60Ω (E0h)	0 ... 60Ω	0 ... 27648	nominal range

Measuring range (funct. no.)	Measuring value	Signal range	Range
	---	---	underrange
4 wire: 0 ... 600Ω (E1h)	705.5Ω	32511	overrange
	0 ... 600Ω	0 ... 27648	nominal range
	---	---	underrange
4 wire: 0 ... 3000Ω (E2h)	3528Ω	32511	overrange
	0 ... 3000Ω	0 ... 27648	nominal range
	---	---	underrange

TC

Temperature

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
Type J: [Fe-Cu-Ni IEC] -210 ... +1200°C -346 ... 2192°F 63.2 ... 1473.2K	+14500	26420	17232	overrange
	-2100 ... +12000	-3460 ... 21920	632 ... 14732	nominal range
	---	---	---	underrange
Type K: [Ni-Cr-Ni] -270 ... +1372°C -454 ... 2501.6°F 0 ... 1645.2K	+16220	29516	18952	overrange
	-2700 ... +13720	-4540 ... 25016	0 ... 16452	nominal range
	---	---	---	underrange
Type N: [Ni-Cr-Si] -270 ... +1300°C -454 ... 2372°F 0 ... 1573.2K	+15500	28220	18232	overrange
	-2700 ... +13000	-4540 ... 23720	0 ... 15732	nominal range
	---	---	---	underrange
Type R: [PtRh-Pt] -50 ... +1769°C -58 ... 3216.2°F 223.2 ... 2042.2K	+20190	32766	22922	overrange
	-500 ... +17690	-580 ... 32162	2232 ... 20422	nominal range
	-1700	-2740	1032	underrange
Type S: [PtRh-Pt] -50 ... +1769°C -58 ... 3216.2°F 223.2 ... 2042.2K	+20190	32766	22922	overrange
	-500 ... +17690	-580 ... 32162	2232 ... 20422	nominal range
	-1700	-2740	1032	underrange
Type T:	+5400	10040	8132	overrange

Measuring ranges and function numbers

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
[Cu-Cu-Ni]	-2700 ... +4000	-4540 ... 7520	32 ... 6732	nominal range
-270 ... +400°C	---	---	---	underrange
-454 ... 752°F				
3.2 ... 673.2K				
Type B:	+20700	32766	23432	overrange
[PtRh-PtRh]	0 ... +18200	320 ... 27865	2732 ... 20932	nominal range
0 ... +1820°C	-1200	-1840	1532	underrange
32 ... 2786.5°F				
273.2 ... 2093.2K				
Type C:	+25000	32766	23432	overrange
[WRe5-WRe26]	0 ... +23150	320 ... 27865	2732 ... 20932	nominal range
0 ... +2315°C	-1200	-1840	1532	underrange
32 ... 2786.5°F				
273.2 ... 2093.2K				
Type E:	+12000	21920	14732	overrange
[Ni-Cr - Cu-Ni]	-2700 ... +10000	-4540 ... 18320	0 ... 12732	nominal range
-270 ... +1000°C	---	---	---	underrange
-454 ... 1832°F				
0 ... 1273.2K				
Type L:	+11500	21020	14232	overrange
[Fe-Cu-Ni]	-2000 ... +9000	-3280 ... 16520	732 ... 11732	nominal range
-200 ... +900°C	---	---	---	underrange
-328 ... 1652°F				
73.2 ... 1173.2K				

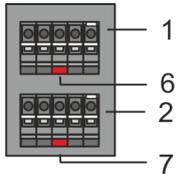
3.4 M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

Properties

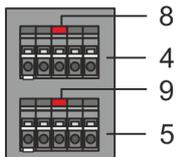
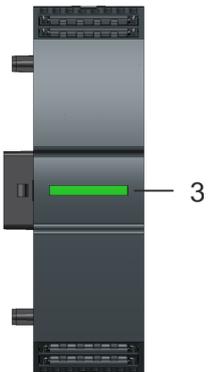
The electronic module has 4 inputs for measuring with parameterizable functions. The channels of the module are isolated to the backplane bus.

- 4 analog inputs
- Voltage measuring
 - Suited for sensors with $\pm 10V$, 0 ... 10V or $\pm 80mV$
- Current measuring
 - Suited for sensors with 0 ... 20mA
 - 4 ... 20mA with external supply
- RTD
 - Suited for resistance-type sensors
0...3000 Ohm: 2, 3 or 4 wire
 - Resistance temperature sensors
Pt100, Pt1000, NI100, NI1000: 2, 3 or 4 wire
- TC
 - Suited for sensors with type
Typ J, K, N, R, S, T, B, C, E, L
- Interrupt and diagnostics function
- 16bit resolution

Structure



- 1 X2: Terminal channel 1
- 2 X1: Terminal channel 0
- 3 Status bar periphery module
- 4 X3: Terminal channel 2
- 5 X4: Terminal channel 3
- 6 X2 AI 1: LED Error channel 1
- 7 X1 AI 0: LED Error channel 0
- 8 X3 AI 2: LED Error channel 2
- 9 X4 AI 3: LED Error channel 3



M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

Status bar

LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

LEDs connectors

Pin		LED	Description
X2	AI Channel 1	red	Error channel x
X1	AI Channel 0	red	<ul style="list-style-type: none"> Signal leaves measuring range Error in parameterization Wire break (RTD and TC, if parameterized)
X3	AI Channel 2	red	
X4	AI Channel 3	red	

Pin assignment

X2: Channel 1		Pin 5: RTD	Pin 4: TC	Pin 3: U/I +	Pin 2: -	Pin 1: M1
		-	-	V +	V -	-
		-	-	A +	A -	-
		-	80mV +	-	80mV -	-
		-	TC +	-	TC -	-
		RTD2 +	-	-	-	RTD2 -
		RTD3 +	RTD3 +	-	RTD3 - ¹	RTD3 -
		RTD4 +	RTD4 +	-	RTD4 -	RTD4 -

X1: Channel 0		Pin 5: RTD	Pin 4: TC	Pin 3: U/I +	Pin 2: -	Pin 1: M0
		-	-	V +	V -	-
		-	-	A +	A -	-
		-	80mV +	-	80mV -	-
		-	TC +	-	TC -	-
		RTD2 +	-	-	-	RTD2 -
		RTD3 +	RTD3 +	-	RTD3 - ¹	RTD3 -
		RTD4 +	RTD4 +	-	RTD4 -	RTD4 -

X3: Channel 2		Pin 1: M2	Pin 2: -	Pin 3: U/I +	Pin 4: TC	Pin 5: RTD
<p>The diagram shows a 5-pin connector labeled X3. Pin 1 is M2, Pin 2 is -, Pin 3 is U/I +, Pin 4 is TC, and Pin 5 is RTD. A voltmeter/ammeter symbol is connected between pins 2 and 3. An 80mV sensor is connected between pins 3 and 4. Below this, three RTD sensors (RTD2, RTD3, RTD4) are shown connected to pins 1, 2, 3, 4, and 5 in various configurations.</p>	-	V -	V +	-	-	
	-	A -	A +	-	-	
	-	80mV -	-	80mV +	-	
	-	TC -	-	TC +	-	
	RTD2 -	-	-	-	RTD2 +	
	RTD3 -	RTD3 - 1	-	RTD3 +	RTD3 +	
	RTD4 -	RTD4 -	-	RTD4 +	RTD4 +	

X4: Channel 3		Pin 1: M3	Pin 2: -	Pin 3: U/I +	Pin 4: TC	Pin 5: RTD
<p>The diagram shows a 5-pin connector labeled X4. Pin 1 is M3, Pin 2 is -, Pin 3 is U/I +, Pin 4 is TC, and Pin 5 is RTD. A voltmeter/ammeter symbol is connected between pins 2 and 3. An 80mV sensor is connected between pins 3 and 4. Below this, three RTD sensors (RTD2, RTD3, RTD4) are shown connected to pins 1, 2, 3, 4, and 5 in various configurations.</p>	-	V -	V +	-	-	
	-	A -	A +	-	-	
	-	80mV -	-	80mV +	-	
	-	TC -	-	TC +	-	
	RTD2 -	-	-	-	RTD2 +	
	RTD3 -	RTD3 - 1	-	RTD3 +	RTD3 +	
	RTD4 -	RTD4 -	-	RTD4 +	RTD4 +	

1) For 3-wire measurement, pin 1 and pin 2 are to be bridged.



*Please take care of the correct polarity when installing the sensors!
Please install short circuits at non-used inputs by connecting the positive contact with the channel ground of the according channel.*



3/4-wire measurement

For 3-wire measurement (RTD3), it is assumed that all 3 wires have the same resistance, while for 4-wire measurement (RTD4), the resistances of the wires are individually measured and taken into account.

Supplementation to the installation guidelines TC

To avoid variations in temperature within the module, which may affect the accuracy of the temperature measurement, you should consider the following points when assembling:

- The module should be in a static condition, i.e. the temperature should be as constant as possible in the environment of your module. Installation horizontally suspended in the closed switchgear cabinet without forced ventilation.
- The accuracy is reached after approx. 30 minutes after entering the static condition.

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

Input area

Addr.	PIQ	Bytes	Function
+0	AI 0	2	Analog value channel 0
+2	AI 1	2	Analog value channel 1
+4	AI 2	2	Analog value channel 2
+6	AI 3	2	Analog value channel 3

Output area

No byte of the output area is used by the module.

3.4.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS
DIAG_EN	1	Diagnostics ¹	00h	00h
WIBRK_EN	1	Wire break recognition (only RTD and TC) ¹	00h	00h
LIMIT_EN	1	Limit value monitoring ¹	00h	00h
RES3	1	reserved	00h	00h
TEMPCNF	1	Temperature system	00h	01h
SUPR	1	Interference frequency suppression (SFU)	02h	01h
RES6	1	reserved	00h	01h
RES7	1	reserved	00h	01h
CH0FN	1	Function number channel 0	10h	80h
CH0FO	1	Function option channel 0	02h	80h
CH0UL	2	Upper limit value channel 0	7FFFh	80h
CH0LL	2	Lower limit value channel 0	8000h	80h
CH1FN	1	Function number channel 1	10h	81h
CH1FO	1	Function option channel 1	02h	81h
CH1UL	2	Upper limit value channel 1	7FFFh	81h
CH1LL	2	Lower limit value channel 1	8000h	81h
CH2FN	1	Function number channel 2	10h	82h
CH2FO	1	Function option channel 2	02h	82h
CH2UL	2	Upper limit value channel 2	7FFFh	82h
CH2LL	2	Lower limit value channel 2	8000h	82h
CH3FN	1	Function number channel 3	10h	83h
CH3FO	1	Function option channel 3	02h	83h
CH3UL	2	Upper limit value channel 3	7FFFh	83h
CH3LL	2	Lower limit value channel 3	8000h	83h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Diagnostic interrupt <ul style="list-style-type: none"> - 00h: disabled - 40h: enabled

- Here you can enable respectively disable the diagnostic interrupt.

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Parameter data

WIBRK_EN Wire-break recognition

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Wire-break recognition channel 0 (1: on) ■ Bit 1: Wire-break recognition channel 1 (1: on) ■ Bit 2: Wire-break recognition channel 2 (1: on) ■ Bit 3: Wire-break recognition channel 3 (1: on) ■ Bit 7 ... 4: reserved



Wire-break recognition is only possible with RTD and TC!



Due to the high sensitivity of the inputs, unused inputs should be deactivated in the parametrization. Due to the high input impedance, open inputs can be influenced by adjacent channels or due to the measuring method during wire break detection. Since the entire measuring range moves in the mV range, open-loop inputs can already cause measuring range overshoots.

LIMIT_EN
Limit value monitoring

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Limit value monitoring channel 0 (1: on) ■ Bit 1: Limit value monitoring channel 1 (1: on) ■ Bit 2: Limit value monitoring channel 2 (1: on) ■ Bit 3: Limit value monitoring channel 3 (1: on) ■ Bit 7 ... 4: reserved

TEMPCNF
Temperature system

Byte	Bit 7 ... 0
0	Temperature system <ul style="list-style-type: none"> ■ Bit 0, 1: Channel 0 ■ Bit 2, 3: Channel 1 ■ Bit 4, 5: Channel 2 ■ Bit 6, 7: Channel 3 <ul style="list-style-type: none"> – 00: °C – 01: °F – 10: K

SUPR Interference frequency suppression (SFU)

Byte	Bit 7 ... 0
0	Interference frequency suppression <ul style="list-style-type: none"> ■ Bit 0, 1: Channel 0 ■ Bit 2, 3: Channel 1 ■ Bit 4, 5: Channel 2 ■ Bit 6, 7: Channel 3 <ul style="list-style-type: none"> - 00: deactivated - 01: 60Hz - 10: 50Hz (Default) - 11: reserved



For RTD and TC input channels the deactivation of the interference frequency suppression is not possible! If the channel is deactivated, the SFU default value for this channel is automatically used!

CHxFN Function number channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. The formulas listed here allow you to transform an evaluated measuring value (analog value) to a value assigned to the measuring range (digital value) and vice versa.



With FFh the corresponding channel is deactivated.

Voltage

0 ... 10V

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
0 ... 10V Siemens S7 format (10h)	11.76V	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{10}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		$U = D \cdot \frac{10}{27648}$
	0V	0	0000h		
	-1.76V	-4864	ED00h	underrange	
0 ... 10V Siemens S5 format (20h)	12.5V	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{10}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		$U = D \cdot \frac{10}{16384}$
	0V	0	0000h		
	-2V	-3277	F333h	underrange	

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Voltage

±10V

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V Siemens S7 format (12h)	11.76V	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{27648}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	-5V	-13824	CA00h		
	-10V	-27648	9400h	underrange	
	-11.76V	-32512	8100h		
±10V Siemens S5 format (22h)	12.5V	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{10}$ $U = D \cdot \frac{10}{16384}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	-5V	-8192	E000h		
	-10V	-16384	C000h	underrange	
	-12.5V	-20480	B000h		

Voltage

-80 ... 80mV

Meas. range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
-80 ... 80mV Siemens S7 format (11h)	94.07mV	32511	7EFFh	overrange	$D = 27648 \cdot \frac{U}{80}$ $U = D \cdot \frac{80}{27648}$
	80mV	27648	6C00h	nominal range	
	0V	0	0000h		
	-80mV	-27648	9400h		
	-94.07mV	-32512	8100h	underrange	
-80 ... 80mV Siemens S5 format (21h)	100mV	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{80}$ $U = D \cdot \frac{80}{16384}$
	80mV	16384	4000h	nominal range	
	0V	0	0000h		
	-80mV	-16384	C000h		
	-100mV	-20480	B000h	underrange	

Current

0(4) ... 20mA

Meas. range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
0 ... 20mA	23.52mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I}{20}$ $I = D \cdot \frac{20}{27648}$
Siemens S7 format (31h)	20mA	27648	6C00h	nominal range	
	10mA	13824	3600h		
	0mA	0	0000h		
	-3.52mA	-4864	ED00h	underrange	
0 ... 20mA	25.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I}{20}$ $I = D \cdot \frac{20}{16384}$
Siemens S5 format (41h)	20mA	16384	4000h	nominal range	
	10mA	8192	2000h		
	0mA	0	0000h		
	-4,00mA	-3277	F333h	underrange	
4 ... 20mA	22.81mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I-4}{16}$ $I = D \cdot \frac{16}{27648} + 4$
Siemens S7 format (30h)	20mA	27648	6C00h	nominal range	
	12mA	13824	3600h		
	4mA	0	0000h		
	1.19mA	-4864	ED00h	underrange	
4 ... 20mA	24.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I-4}{16}$ $I = D \cdot \frac{16}{16384} + 4$
Siemens S5 format (40h)	20mA	16384	4000h	nominal range	
	12mA	8192	2000h		
	4mA	0	0000h		
	0.8mA	-3277	F333h	underrange	

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Parameter data

RTD

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: PT100 (50h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
2 wire: PT1000 (51h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
2 wire: NI100 (52h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
2 wire: NI1000 (53h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
3 wire: PT100 (58h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
3 wire: PT1000 (59h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
3 wire: NI100 (5Ah)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
3 wire: NI1000 (5Bh)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
4 wire: PT100 (60h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
4 wire: PT1000 (61h)	+1000°C	+10000	overrange
	-200 ... +850°C	-2000 ... +8500	nominal range
	-243°C	-2430	underrange
4 wire: NI100 (62h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange
4 wire: NI1000 (63h)	+295°C	+2950	overrange
	-60 ... +250°C	-600 ... +2500	nominal range
	-105°C	-1050	underrange

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: 0 ... 60Ω (70h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 600Ω (71h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 3000Ω (72h)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 60Ω (78h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 600Ω (79h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
3 wire: 0 ... 3000Ω (7Ah)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 60Ω (80h)	---	---	overrange
	0 ... 60Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 600Ω (81h)	---	---	overrange
	0 ... 600Ω	0 ... 32767	nominal range
	---	---	underrange
4 wire: 0 ... 3000Ω (82h)	---	---	overrange
	0 ... 3000Ω	0 ... 32767	nominal range
	---	---	underrange
2 wire: 0 ... 60Ω (90h)	---	---	overrange
	0 ... 60Ω	0 ... 6000	nominal range
	---	---	underrange
2 wire: 0 ... 600Ω (91h)	---	---	overrange
	0 ... 600Ω	0 ... 6000	nominal range
	---	---	underrange
2 wire: 0 ... 3000Ω (92h)	---	---	overrange
	0 ... 3000Ω	0 ... 30000	nominal range
	---	---	underrange
3 wire: 0 ... 60Ω	---	---	overrange

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Measuring range (funct. no.)	Measuring value	Signal range	Range
(98h)	0 ... 60Ω	0 ... 6000	nominal range
	---	---	underrange
3 wire: 0 ... 600Ω (99h)	---	---	overrange
	0 ... 600Ω	0 ... 6000	nominal range
3 wire: 0 ... 3000Ω (9Ah)	---	---	underrange
	0 ... 3000Ω	0 ... 30000	nominal range
4 wire: 0 ... 60Ω (A0h)	---	---	underrange
	0 ... 60Ω	0 ... 6000	nominal range
4 wire: 0 ... 600Ω (A1h)	---	---	overrange
	0 ... 600Ω	0 ... 6000	nominal range
4 wire: 0 ... 3000Ω (A2h)	---	---	underrange
	0 ... 3000Ω	0 ... 30000	nominal range
2 wire: 0 ... 60Ω (D0h)	---	---	overrange
	70.55Ω	32511	overrange
	0 ... 60Ω	0 ... 27648	nominal range
2 wire: 0 ... 600Ω (D1h)	---	---	underrange
	705.5Ω	32511	overrange
	0 ... 600Ω	0 ... 27648	nominal range
2 wire: 0 ... 3000Ω (D2h)	---	---	underrange
	3528Ω	32511	overrange
	0 ... 3000Ω	0 ... 27648	nominal range
3 wire: 0 ... 60Ω (D8h)	---	---	underrange
	70.55Ω	32511	overrange
	0 ... 60Ω	0 ... 27648	nominal range
3 wire: 0 ... 600Ω (D9h)	---	---	underrange
	705.5Ω	32511	overrange
	0 ... 600Ω	0 ... 27648	nominal range
3 wire: 0 ... 3000Ω (DAh)	---	---	underrange
	3528Ω	32511	overrange
	0 ... 3000Ω	0 ... 27648	nominal range
4 wire: 0 ... 60Ω (E0h)	---	---	underrange
	70.55Ω	32511	overrange
	0 ... 60Ω	0 ... 27648	nominal range

Measuring range (funct. no.)	Measuring value	Signal range	Range
	---	---	underrange
4 wire: 0 ... 600Ω (E1h)	705.5Ω	32511	overrange
	0 ... 600Ω	0 ... 27648	nominal range
	---	---	underrange
4 wire: 0 ... 3000Ω (E2h)	3528Ω	32511	overrange
	0 ... 3000Ω	0 ... 27648	nominal range
	---	---	underrange

TC

Temperature

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
Type J: [Fe-Cu-Ni IEC] -210 ... +1200°C -346 ... 2192°F 63.2 ... 1473.2K	+14500	26420	17232	overrange
	-2100 ... +12000	-3460 ... 21920	632 ... 14732	nominal range
	---	---	---	underrange
Type K: [Ni-Cr-Ni] -270 ... +1372°C -454 ... 2501.6°F 0 ... 1645.2K	+16220	29516	18952	overrange
	-2700 ... +13720	-4540 ... 25016	0 ... 16452	nominal range
	---	---	---	underrange
Type N: [Ni-Cr-Si] -270 ... +1300°C -454 ... 2372°F 0 ... 1573.2K	+15500	28220	18232	overrange
	-2700 ... +13000	-4540 ... 23720	0 ... 15732	nominal range
	---	---	---	underrange
Type R: [PtRh-Pt] -50 ... +1769°C -58 ... 3216.2°F 223.2 ... 2042.2K	+20190	32766	22922	overrange
	-500 ... +17690	-580 ... 32162	2232 ... 20422	nominal range
	-1700	-2740	1032	underrange
Type S: [PtRh-Pt] -50 ... +1769°C -58 ... 3216.2°F 223.2 ... 2042.2K	+20190	32766	22922	overrange
	-500 ... +17690	-580 ... 32162	2232 ... 20422	nominal range
	-1700	-2740	1032	underrange
Type T:	+5400	10040	8132	overrange

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Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
[Cu-Cu-Ni]	-2700 ... +4000	-4540 ... 7520	32 ... 6732	nominal range
-270 ... +400°C	---	---	---	underrange
-454 ... 752°F				
3.2 ... 673.2K				
Type B:	+20700	32766	23432	overrange
[PtRh-PtRh]	0 ... +18200	320 ... 27865	2732 ... 20932	nominal range
0 ... +1820°C	-1200	-1840	1532	underrange
32 ... 2786.5°F				
273.2 ... 2093.2K				
Type C:	+25000	32766	23432	overrange
[WRe5-WRe26]	0 ... +23150	320 ... 27865	2732 ... 20932	nominal range
0 ... +2315°C	-1200	-1840	1532	underrange
32 ... 2786.5°F				
273.2 ... 2093.2K				
Type E:	+12000	21920	14732	overrange
[Ni-Cr - Cu-Ni]	-2700 ... +10000	-4540 ... 18320	0 ... 12732	nominal range
-270 ... +1000°C	---	---	---	underrange
-454 ... 1832°F				
0 ... 1273.2K				
Type L:	+11500	21020	14232	overrange
[Fe-Cu-Ni]	-2000 ... +9000	-3280 ... 16520	732 ... 11732	nominal range
-200 ... +900°C	---	---	---	underrange
-328 ... 1652°F				
73.2 ... 1173.2K				

**CHxFO Function option
channel x**

Depending on the Interference frequency suppression for each channel the transducer velocity may be set.

Code	Measuring range	Velocity (in ms) / channel at interference frequency suppression	
		50Hz	60Hz
	U/I	30 (16bit)	30 (16bit)
01h ²	RTD / TC $\pm 80\text{mV}$	200 (16bit)	200 (16bit)
02h ^{1, 2}		100 (16bit)	100 (16bit)
03h		-	40 (16bit)
04h		-	34 (16bit)
05h		-	20 (15bit)
06h		-	17 (14bit)
07h		-	10 (13bit)

1) Default

2) For Code 01h and 02h the tolerances of the technical data "with interference frequency suppression" are valid.

CHxUL / CHxLL Channel x

For each channel an *upper* and a *lower limit* may be defined. By presetting 7FFFh for the upper respectively 8000h for the lower limit value the corresponding limit is deactivated. If an adjusted limit value is outside the allowed range, no process interrupt is initialized, but the limit will never be reached.

3.4.2 Diagnostics and interrupt

Event	Process interrupt	Diagnostics interrupt	parameterizable
Error in project engineering/param.	-	X	-
Wire break (only RTD and TC)	-	X	X
Measuring range overflow	-	X	-
Measuring range underflow	-	X	-
Limit overflow	X	-	X
Limit underflow	X	-	X
Diagnostic buffer overflow	-	X	-
Communication error	-	X	-
Process interrupt lost	-	X	-

Process interrupt

So you may react to asynchronous events, there is the possibility to activate a process interrupt. A process interrupt interrupts the linear program sequence and jumps depending on the master system to a corresponding Interrupt routine. Here you can react to the process interrupt accordingly.

Operating with CPU, PROFIBUS and PROFINET the process interrupt data were transferred via diagnostics telegram.

Name	Bytes	Function	Default
PRIT_OL	1	Limit overflow channel x	00h
PRIT_UL	1	Limit underflow channel x	00h
PRIT_US	2	µs-Ticker	00h

PRIT_OL Limit overflow

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Limit overflow channel 0 ■ Bit 1: Limit overflow channel 1 ■ Bit 2: Limit overflow channel 2 ■ Bit 3: Limit overflow channel 3 ■ Bit 7 ... 4: reserved

PRIT_UL Limit underflow

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Limit underflow channel 0 ■ Bit 1: Limit underflow channel 1 ■ Bit 2: Limit underflow channel 2 ■ Bit 3: Limit underflow channel 3 ■ Bit 7 ... 4: reserved

PRIT_US μ s ticker

Byte	Bit 7 ... 0
0 ... 1	16bit μ s value at the moment of the interrupt

 μ s ticker

In the module there is a 32 bit timer (μ s ticker). With PowerON the timer starts counting with 0. After $2^{32}-1\mu$ s the timer starts with 0 again. PRIT_US represents the lower 2 byte of the μ s ticker value ($0 \dots 2^{16}-1$).

Diagnostic data

The diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Wire-break only RTD and TC (if parameterized)
- External auxiliary supply missing

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
RES2	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	71h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	02h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR...CH7ERR	4	reserved	00h	
DIAG_US	4	μ s ticker	00h	

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at module failure ■ Bit 1: set at internal error ■ Bit 2: set at external error ■ Bit 3: set at channel error ■ Bit 6 ... 4: reserved ■ Bit 7: set at error in parameterization

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MODTYP Module information

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 3 ... 0: module class <ul style="list-style-type: none"> – 0101b: Analog module ■ Bit 4: Channel information available ■ Bit 7 ... 5: reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 3 ... 0: reserved ■ Bit 4: set at internal communication error ■ Bit 5: reserved ■ Bit 6: process interrupt lost ■ Bit 7: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 6 ... 0: Channel type <ul style="list-style-type: none"> – 71h: Analog input ■ Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostic bits per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

CHERR Channel error

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at error in channel group 0 ■ Bit 1: set at error in channel group 1 ■ Bit 2: set at error in channel group 2 ■ Bit 3: set at error in channel group 3 ■ Bit 7 ... 4: reserved

CHxERR Channel-specific

Byte	Bit 7 ... 0
0	Channel-specific error: Channel x: <ul style="list-style-type: none"> ■ Bit 0: set at project engineering/parameterization error ■ Bit 3 ... 1: reserved ■ Bit 4: set at wire break (only RTD and TC) ■ Bit 5: set at process interrupt lost ■ Bit 6: set at measuring range underflow ■ Bit 7: set at measuring range overflow

DIAG_US μ s ticker

Byte	Bit 7 ... 0
0...3	Value of the μ s ticker at the moment of the diagnostic <ul style="list-style-type: none">■ In the System MICRO module there is a timer (μs ticker). With PowerON the timer starts counting with 0. After $2^{32}-1\mu$s the timer starts with 0 again.

3.4.3 Technical data

Order no.	M31-1CD50
Type	SM M31 - Analog input
Module ID	0417 1544
Current consumption/power loss	
Current consumption from backplane bus	150 mA
Power loss	750 mW
Technical data analog inputs	
Number of inputs	4
Cable length, shielded	200 m
Rated load voltage	-
Current consumption from load voltage L+ (without load)	-
Voltage inputs	✓
Min. input resistance (voltage range)	100 kΩ
Input voltage ranges	0 V ... +10 V -10 V ... +10 V -80 mV ... +80 mV
Operational limit of voltage ranges	+/-0.3%
Operational limit of voltage ranges with SFU	+/-0.3%
Basic error limit voltage ranges	+/-0.2%
Basic error limit voltage ranges with SFU	+/-0.2%
Destruction limit voltage	max. 30V
Current inputs	✓
Max. input resistance (current range)	70 Ω
Input current ranges	0 mA ... +20 mA +4 mA ... +20 mA
Operational limit of current ranges	+/-0.3%
Operational limit of current ranges with SFU	+/-0.3%
Basic error limit current ranges	+/-0.2%
Radical error limit current ranges with SFU	+/-0.2%
Destruction limit current inputs (voltage)	max. 30V
Destruction limit current inputs (electrical current)	max. 60mA
Resistance inputs	✓
Resistance ranges	0 ... 60 Ohm 0 ... 600 Ohm 0 ... 3000 Ohm
Operational limit of resistor ranges	+/-0.3%
Operational limit of resistor ranges with SFU	+/-0.3%
Basic error limit	+/-0.2%

Order no.	M31-1CD50
Basic error limit with SFU	+/-0.2%
Destruction limit resistance inputs	max. 30V
Resistance thermometer inputs	✓
Resistance thermometer ranges	Pt100 Pt1000 Ni100 Ni1000
Operational limit of resistance thermometer ranges	+/-0.3%
Operational limit of resistance thermometer ranges with SFU	+/-0.3%
Basic error limit thermoresistor ranges	+/-0.2%
Basic error limit thermoresistor ranges with SFU	+/-0.2%
Destruction limit resistance thermometer inputs	max. 30V
Thermocouple inputs	✓
Thermocouple ranges	type J type L type K type N type R type S type B type C type E type T
Operational limit of thermocouple ranges	for type B: +/-14.6K; for type K, for type N: +/-11.0K; for type S, for type R: +/-14.1K; for type T: +/-12.0K; for type C: +/-14.0K; for type E: +/-13.0K; for type J: +/-11.0K; for type L: +/-13.5K
Operational limit of thermocouple ranges with SFU	for type B: +/-14.6K; for type K, Typ N: +/-10.0K; for type S, for type R: +/-14.1K; for type T: +/-12.0K; for type C: +/-14.0K; for type E: +/-13.0K; for type J: +/-11.0K; for type L: +/-13.5K
Basic error limit thermocouple ranges	for type B: +/-14.6K; for type K, type N: +/-10.0K; for type S, for type R: +/-14.1K; for type T: +/-12.0K; for type C: +/-14.0K; for type E: +/-13.0K; for type J: +/-11.0K; for type L: +/-13.5K
Basic error limit thermocouple ranges with SFU	for type B: +/-14.6K; for type K, Typ N: +/-10.0K; for type S, type R: +/-14.1K; for type T: +/-12.0K; for type C: +/-14.0K; for type E: +/-13.0K; for type J: +/-11.0K; for type L: +/-13.5K
Destruction limit thermocouple inputs	max. 30V
Programmable temperature compensation	-
External temperature compensation	-
Internal temperature compensation	✓

Order no.	M31-1CD50
Temperature error internal compensation	8 K
Technical unit of temperature measurement	°C, °F, K
Resolution in bit	16
Measurement principle	Sigma-Delta
Basic conversion time	10ms ... 200ms (for R/RTD & TC)
Noise suppression for frequency	>80dB (UCM <3,2V)
Status information, alarms, diagnostics	
Status display	Bicolour green/red LED
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes, parameterizable
Diagnostics information read-out	possible
Module state	none
Module error display	Bicolour green/red LED
Channel error display	red LED per channel
Isolation	
Between channels	✓
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	-
Max. potential difference between circuits	-
Max. potential difference between inputs (Ucm)	DC 3 V
Max. potential difference between Mana and Mintern (Uiso)	DC 75 V/ AC 50 V
Max. potential difference between inputs and Mana (Ucm)	-
Max. potential difference between inputs and Mintern (Uiso)	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	-
Datasizes	
Input bytes	8
Output bytes	0
Parameter bytes	32
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm

Order no.	M31-1CD50
Mechanical data	
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm
Net weight	88 g
Weight including accessories	88 g
Gross weight	105 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-40 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

Information on error limits

The indicated error limits are valid starting from the following temperatures:

- Thermoelement type L: -100 °C
- Thermoelement type T: -90 °C
- Thermoelement type K: -60 °C
- Thermoelement type B: +70 °C
- Thermoelement type N: -80 °C
- Thermoelement type E: -150 °C
- Thermoelement type R: +200 °C
- Thermoelement type S: +100 °C
- Thermoelement type J: -140 °C

4 Analog output

4.1 General

Cabling for analog signals

You must only use screened cable when you are connecting analog signals. These cables reduce the effect of electrical interference. The screen of the analog signal cable should be grounded at both ends. In situations with different electrical potentials, it is possible that a current will flow to equalize the potential difference. This current could interfere with the analog signals. Under these circumstances it is advisable to ground the screen of the signal cable at one end only.

Connecting loads and actuators

You can use the analog output modules to supply loads and actuators with current or voltage.



Please take always care of the correct polarity when connecting actuators! Please leave the output clamps of not used channels disconnected and set the output type of the channel to "deactivated" in the hardware configurator from Siemens.

Parameterization

The parameterization via CPU, PROFIBUS and PROFINET happens by means of record sets (DS). The corresponding record set number may be found at the respective module description.

Diagnostic functions

The modules have diagnostics capability. The following errors may release a diagnostic:

- Error in parameterization
- Short-circuit recognition
- Wire-break recognition



Alternated blinking of the channel error LEDs

The alternate blinking of the channel error LEDs of channel 0 and 1 indicates a watchdog error due to a system overload. Restart with a power cycle your system. If the error occurred again, check configuration and circuit and adjust them if necessary. If the error persists, please contact our support.

4.2 Analog value

Analog value representation

The analog values are only processed in binary representation. Hereby the binary word variable is transformed into an analog process signal and put out via the corresponding channel. The analog values are displayed as a fixed-point number in the two's complement.

Resolution	Analog value - twos complement															
	High byte (byte 0)								Low byte (byte 1)							
Bit number	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Value	SG	2^{14}	2^{13}	2^{12}	2^{11}	2^{10}	2^9	2^8	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0
15Bit+SG	SG	Analog value (word)														

Sign bit (SG)

The algebraic sign bit is represented by Bit 15. Here it is essential:

- Bit 15 = "0": → positive value
- Bit 15 = "1": → negative value

4.3 Output ranges and function numbers

General

In the following there are the output ranges listed with function number, which were supported by the corresponding analog module. The here listed formulas allow you to transform a value (digital value) to an analog value and vice versa.

Voltage

0 ... 10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
0 ... 10V Siemens S7 format (10h)	11,76V	32511	7EFFh	overrange	$U = D \times \frac{10}{27648}$ $D = 27648 \times \frac{U}{10}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	Not possible, is limited to 0V.				
0 ... 10V Siemens S5 format (20h)	12,5V	20480	5000h	overrange	$U = D \times \frac{10}{16384}$ $D = 16384 \times \frac{U}{10}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	Not possible, is limited to 0V.				

Output ranges and function numbers

±10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V Siemens S7 format (12h)	11.76V	32511	7EFFh	overrange	$U = D \times \frac{10}{27648}$ $D = 27648 \times \frac{U}{10}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	-5V	-13824	CA00h		
	-10V	-27648	9400h	underrange	
	-11.76V	-32512	8100h		
±10V Siemens S5 format (22h)	12.5V	20480	5000h	overrange	$U = D \times \frac{10}{16384}$ $D = 16384 \times \frac{U}{10}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	-5V	-8192	E000h		
	-10V	-16384	C000h	underrange	
	-12.5V	-20480	B000h		

Current**0 ... 20mA**

Output range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
0 ... 20mA Siemens S7 format (31h)	23.52mA	32511	7EFFh	overrange	$I = D \times \frac{20}{27648}$ $D = 27648 \times \frac{I}{20}$
	20mA	27648	6C00h	nominal range	
	10mA	13824	3600h		
	0mA	0	0000h		
	Not possible, is limited to 0mA.				
0 ... 20mA Siemens S5 format (41h)	25.00mA	20480	5000h	overrange	$I = D \times \frac{20}{16384}$ $D = 16384 \times \frac{I}{20}$
	20mA	16384	4000h	nominal range	
	10mA	8192	2000h		
	0mA	0	0000h		
	Not possible, is limited to 0mA.				

4 ... 20mA

Output range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
4 ... 20mA Siemens S7 format (30h)	22.81mA	32511	7EFFh	overrange	$I = D \times \frac{16}{27648} + 4$ $D = 27648 \times \frac{I-4}{16}$
	20mA	27648	6C00h	nominal range	
	12mA	13824	3600h		
	4mA	0	0000h		
	0mA	-6912	E500h	underrange	
4 ... 20mA Siemens S5 format (40h)	24.00mA	20480	5000h	overrange	$I = D \times \frac{16}{16384} + 4$ $D = 16384 \times \frac{I-4}{16}$
	20mA	16384	4000h	nominal range	
	12mA	8192	2000h		
	4mA	0	0000h		
	0mA	-4096	F000h	underrange	

M32-1BD40 - AO 4 x 12Bit I

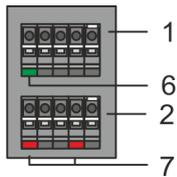
4.4 M32-1BD40 - AO 4 x 12Bit I

Properties

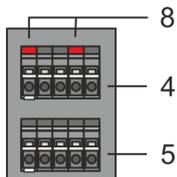
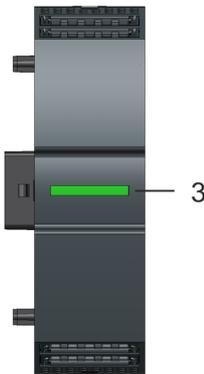
The Analog module has 4 outputs with parameterizable functions. The channels of the module are electrically isolated from the backplane bus. In addition, the channels are isolated to the DC 24V power supply by means of DC/DC converter.

- 4 analog outputs
- Suited for sensors with 0...20mA; 4...20mA
- Diagnostics function
- 12bit resolution

Structure



- 1 X2: Terminal (DC 24V)
- 2 X1: Terminal (AO 0, AO 1)
- 3 Status bar periphery module
- 4 X3: Terminal (AO 2, AO 3)
- 5 X4: Terminal (Shield)
- 6 X2 1L+: LED DC 24V electronic section supply
- 7 X1 AO 0, AO 1: LED channel error
- 8 X3 AO 2, AO 3: LED channel error



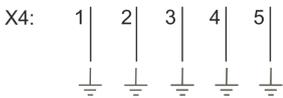
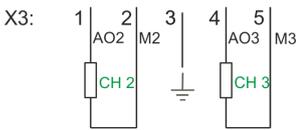
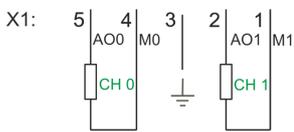
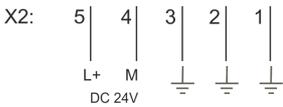
Status bar

LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

LEDs connectors

Pin	Function	LED	Description
X2:5	L+	green	DC 24V electronic section supply OK
X1:5	AO 0	red	Error channel x ■ Error in parameterization ■ Wire break (if parameterized)
X1:2	AO 1	red	
X3:1	AO 2	red	
X3:4	AO 3	red	

Pin assignment



	Pin	Function	Type	LED	Description
X2:	1	⏏	O		Shield
	2	⏏	O		Shield
	3	⏏	I		Shield
	4	M	I		Ground power supply (M)
	5	L+	I	green	Power supply DC 24V (L+)
X1:	1	M1	O		Ground CH 1
	2	AO1	O	red	Analog Output CH 1
	3	⏏	O		Shield
	4	M0	O		Ground CH 0
	5	AO0	O	red	Analog Output CH 0
X3:	1	AO2	O	red	Analog Output CH 2
	2	M2	O		Ground CH 2
	3	⏏	O		Shield
	4	AO3	O	red	Analog Output CH 3
	5	M3	O		Ground CH 3
X4:	1	⏏	O		Shield
	2	⏏	O		Shield
	3	⏏	O		Shield
	4	⏏	O		Shield
	5	⏏	O		Shield

I: Input | O: Output

Input area

No byte of the input area is used by the module.

M32-1BD40 - AO 4 x 12Bit I > Parameter data

Output area

Addr.	Name	Byte	Function
+0	PIQ	0	Status of the outputs <ul style="list-style-type: none"> ■ Bit 0: Channel CH 0 ■ Bit 1: Channel CH 1 ■ Bit 2: Channel CH 2 ■ Bit 3: Channel CH 3

4.4.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS
RES0	1	reserved	00h	00h
WIBRK_EN	1	Wire-break recognition	00h	00h
CH0FN	1	Function number channel 0	31h	80h
CH1FN	1	Function number channel 1	31h	81h
CH2FN	1	Function number channel 2	31h	82h
CH3FN	1	Function number channel 3	31h	83h

WIBRK_EN Wire-break recognition

You also can activate the wire-break recognition for the current output range 0 ... 20mA. To ensure a safe wire-break recognition, the decimal value for the output is ≥ 100 .

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Wire-break recognition channel 0 (1: on) ■ Bit 1: Wire-break recognition channel 1 (1: on) ■ Bit 2: Wire-break recognition channel 2 (1: on) ■ Bit 3: Wire-break recognition channel 3 (1: on) ■ Bit 7 ... 4: reserved

CHxFN Function number channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. With FFh the corresponding channel is deactivated. The formulas listed here allow you to transform an evaluated measuring value (digital value) to a value assigned to the measuring range (analog value) and vice versa.

0 ... 20mA

Output range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
0 ... 20mA Siemens S7 format (31h)	23.52mA	32511	7EFFh	overrange	$I = D \times \frac{20}{27648}$ $D = 27648 \times \frac{I}{20}$
	20mA	27648	6C00h	nominal range	
	10mA	13824	3600h		
	0mA	0	0000h		
	Not possible, is limited to 0mA.				
0 ... 20mA Siemens S5 format (41h)	25.00mA	20480	5000h	overrange	$I = D \times \frac{20}{16384}$ $D = 16384 \times \frac{I}{20}$
	20mA	16384	4000h	nominal range	
	10mA	8192	2000h		
	0mA	0	0000h		
	Not possible, is limited to 0mA.				

4 ... 20mA

Output range (funct. no.)	Current (I)	Decimal (D)	Hex	Range	Formulas
4 ... 20mA Siemens S7 format (30h)	22.81mA	32511	7EFFh	overrange	$I = D \times \frac{16}{27648} + 4$ $D = 27648 \times \frac{I-4}{16}$
	20mA	27648	6C00h	nominal range	
	12mA	13824	3600h		
	4mA	0	0000h		
	0mA	-6912	E500h	underrange	
4 ... 20mA Siemens S5 format (40h)	24.00mA	20480	5000h	overrange	$I = D \times \frac{16}{16384} + 4$ $D = 16384 \times \frac{I-4}{16}$
	20mA	16384	4000h	nominal range	
	12mA	8192	2000h		
	4mA	0	0000h		
	0mA	-4096	F000h	underrange	

4.4.2 Diagnostic data

So this module does not support interrupt functions, the diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Wire-break (if parameterized)
- External auxiliary supply missing

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
ERR_C	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	73h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	04h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR...CH7ERR	4	reserved	00h	
DIAG_US	4	µs ticker	00h	

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at module failure ■ Bit 1: set at internal error ■ Bit 2: set at external error ■ Bit 3: set at channel error ■ Bit 4: set at external auxiliary supply missing ■ Bit 6 ... 5: reserved ■ Bit 7: set at error in parametrization

MODTYP Module information

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 3 ... 0: module class <ul style="list-style-type: none"> – 0101b: Analog module ■ Bit 4: Channel information available ■ Bit 7 ... 5: reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 2 ... 0: reserved ■ Bit 3: set at internal diagnostics buffer overflow ■ Bit 4: set at internal communication error ■ Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 6 ... 0: Channel type <ul style="list-style-type: none"> - 73h: Analog output ■ Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostic bits per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

CHERR Channel error

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at error in channel group 0 ■ Bit 1: set at error in channel group 1 ■ Bit 2: set at error in channel group 2 ■ Bit 3: set at error in channel group 3 ■ Bit 7 ... 4: reserved

**CH0ERR ... CH3ERR
Channel-specific**

Byte	Bit 7 ... 0
0	Channel-specific error channel x: <ul style="list-style-type: none"> ■ Bit 0: set at configuring/parameter assignment error ■ Bit 3 ... 1: reserved ■ Bit 4: set at wire-break ■ Bit 7 ... 5: reserved

DIAG_US μ s ticker

Byte	Bit 7 ... 0
0...3	Value of the μ s ticker at the moment of the diagnostic <ul style="list-style-type: none"> ■ In the System MICRO module there is a timer (μs ticker). With PowerON the timer starts counting with 0. After $2^{32}-1\mu$s the timer starts with 0 again.

4.4.3 Technical data

Order no.	M32-1BD40
Type	SM M32 - Analog output
Module ID	0504 25E0
Current consumption/power loss	
Current consumption from backplane bus	70 mA
Current consumption from load voltage L+ (without load)	18 mA
Power loss	0.8 W
Technical data analog outputs	
Number of outputs	4
Cable length, shielded	200 m
Rated load voltage	DC 24 V
Reverse polarity protection of rated load voltage	✓
Current consumption from rated load voltage	-
Voltage output short-circuit protection	-
Voltage outputs	-
Min. load resistance (voltage range)	-
Max. capacitive load (current range)	-
Max. inductive load (current range)	-
Output voltage ranges	-
Operational limit of voltage ranges	-
Basic error limit voltage ranges	-
Destruction limit against external applied voltage	-
Current outputs	-
Max. in load resistance (current range)	350 Ω
Max. inductive load (current range)	10 μH
Typ. open circuit voltage current output	12 V
Output current ranges	0 mA ... +20 mA +4 mA ... +20 mA
Operational limit of current ranges	+/-0.4% ... +/-0.5%
Basic error limit current ranges	+/-0.2% ... +/-0.3%
Destruction limit against external applied voltage	max. 12V (30V for 1s)
Settling time for ohmic load	0.25 ms
Settling time for capacitive load	-
Settling time for inductive load	1.5 ms
Resolution in bit	12
Conversion time	2 ms all channels
Substitute value can be applied	no
Output data size	8 Byte

Order no.	M32-1BD40
Status information, alarms, diagnostics	
Status display	yes
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	yes
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	Bicolour green/red LED
Channel error display	red LED per channel
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	✓
Max. potential difference between circuits	-
Max. potential difference between inputs (U _{cm})	-
Max. potential difference between Mana and Mintern (U _{iso})	DC 75 V/ AC 50 V
Max. potential difference between inputs and Mana (U _{cm})	-
Max. potential difference between inputs and Mintern (U _{iso})	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	DC 500 V
Datasizes	
Input bytes	0
Output bytes	8
Parameter bytes	10
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm
Net weight	94 g
Weight including accessories	94 g
Gross weight	107 g
Environmental conditions	

M32-1BD40 - AO 4 x 12Bit I > Technical data

Order no.	M32-1BD40
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

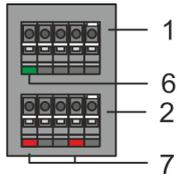
4.5 M32-1BD70 - AO 4 x 12Bit U

Properties

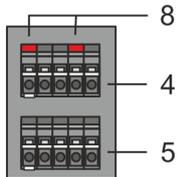
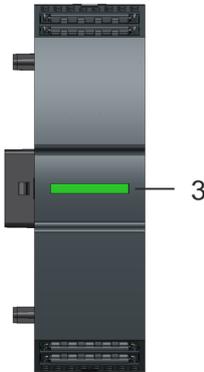
The Analog module has 4 outputs with parameterizable functions. The channels of the module are electrically isolated from the backplane bus. In addition, the channels are isolated to the DC 24V power supply by means of DC/DC converter.

- 4 analog outputs
- Suited for sensors with $\pm 10V$, 0 ... 10V
- Diagnostics function
- 12bit resolution

Structure



- 1 X2: Terminal (DC 24V)
- 2 X1: Terminal (AO 0, AO 1)
- 3 Status bar periphery module
- 4 X3: Terminal (AO 2, AO 3)
- 5 X4: Terminal (Shield)
- 6 X2 1L+: LED DC 24V electronic section supply
- 7 X1 AO 0, AO 1: LED channel error
- 8 X3 AO 2, AO 3: LED channel error



Status bar

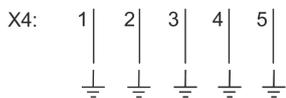
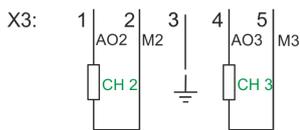
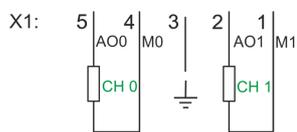
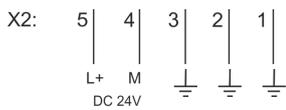
LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

M32-1BD70 - AO 4 x 12Bit U

LEDs connectors

Pin	Function	LED	Description
X2:5	L+	green	DC 24V electronic section supply OK
X1:5	AO 0	red	Error channel x ■ Error in parameterization ■ Wire break (if parameterized)
X1:2	AO 1	red	
X3:1	AO 2	red	
X3:4	AO 3	red	

Pin assignment



	Pin	Function	Type	LED	Description
X2:	1	⏏	O		Shield
	2	⏏	O		Shield
	3	⏏	I		Shield
	4	M	I		Ground power supply (M)
	5	L+	I	green	Power supply DC 24V (L+)
X1:	1	M1	O		Ground CH 1
	2	AO1	O	red	Analog Output CH 1
	3	⏏	O		Shield
	4	M0	O		Ground CH 0
	5	AO0	O	red	Analog Output CH 0
X3:	1	AO2	O	red	Analog Output CH 2
	2	M2	O		Ground CH 2
	3	⏏	O		Shield
	4	AO3	O	red	Analog Output CH 3
	5	M3	O		Ground CH 3
X4:	1	⏏	O		Shield
	2	⏏	O		Shield
	3	⏏	O		Shield
	4	⏏	O		Shield
	5	⏏	O		Shield

I: Input | O: Output

Input area

No byte of the input area is used by the module.

Output area

Addr.	Name	Byte	Function
+0	PIQ	0	Status of the outputs <ul style="list-style-type: none"> ■ Bit 0: Channel CH 0 ■ Bit 1: Channel CH 1 ■ Bit 2: Channel CH 2 ■ Bit 3: Channel CH 3

4.5.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS
RES0	1	reserved	00h	00h
SHORT_EN	1	Short-circuit recognition	00h	00h
CH0FN	1	Function number channel 0	12h	80h
CH1FN	1	Function number channel 1	12h	81h
CH2FN	1	Function number channel 2	12h	82h
CH3FN	1	Function number channel 3	12h	83h

SHORT_EN Short-circuit recognition

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: Short-circuit recognition channel 0 (1: on) ■ Bit 1: Short-circuit recognition channel 1 (1: on) ■ Bit 2: Short-circuit recognition channel 2 (1: on) ■ Bit 3: Short-circuit recognition channel 3 (1: on) ■ Bit 7 ... 4: reserved

CHxFN Function number channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. With FFh the corresponding channel is deactivated. The formulas listed here allow you to transform an evaluated measuring value (digital value) to a value assigned to the measuring range (analog value) and vice versa.

M32-1BD70 - AO 4 x 12Bit U > Parameter data

±10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V Siemens S7 format (12h)	11.76V	32511	7EFFh	overrange	$U = D \times \frac{10}{27648}$ $D = 27648 \times \frac{U}{10}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	-5V	-13824	CA00h		
	-10V	-27648	9400h	underrange	
	-11.76V	-32512	8100h		
±10V Siemens S5 format (22h)	12.5V	20480	5000h	overrange	$U = D \times \frac{10}{16384}$ $D = 16384 \times \frac{U}{10}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	-5V	-8192	E000h		
	-10V	-16384	C000h	underrange	
	-12.5V	-20480	B000h		

0 ... 10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
0 ... 10V Siemens S7 format (10h)	11,76V	32511	7EFFh	overrange	$U = D \times \frac{10}{27648}$ $D = 27648 \times \frac{U}{10}$
	10V	27648	6C00h	nominal range	
	5V	13824	3600h		
	0V	0	0000h		
	Not possible, is limited to 0V.				
0 ... 10V Siemens S5 format (20h)	12,5V	20480	5000h	overrange	$U = D \times \frac{10}{16384}$ $D = 16384 \times \frac{U}{10}$
	10V	16384	4000h	nominal range	
	5V	8192	2000h		
	0V	0	0000h		
	Not possible, is limited to 0V.				

4.5.2 Diagnostic data

So this module does not support interrupt functions, the diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Short-circuit/overload (if parameterized)

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
ERR_C	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	73h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	04h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR...CH7ERR	4	reserved	00h	
DIAG_US	4	µs ticker	00h	

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at module failure ■ Bit 1: set at internal error ■ Bit 2: set at external error ■ Bit 3: set at channel error ■ Bit 4: set at external auxiliary supply missing ■ Bit 6 ... 5: reserved ■ Bit 7: set at error in parametrization

MODTYP Module information

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 3 ... 0: module class <ul style="list-style-type: none"> - 0101b: Analog module ■ Bit 4: Channel information available ■ Bit 7 ... 5: reserved

M32-1BD70 - AO 4 x 12Bit U > Diagnostic data

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 2 ... 0: reserved ■ Bit 3: set at internal diagnostics buffer overflow ■ Bit 4: set at internal communication error ■ Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 6 ... 0: Channel type <ul style="list-style-type: none"> – 73h: Analog output ■ Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostic bits per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

CHERR Channel error

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> ■ Bit 0: set at error in channel group 0 ■ Bit 1: set at error in channel group 1 ■ Bit 2: set at error in channel group 2 ■ Bit 3: set at error in channel group 3 ■ Bit 7 ... 4: reserved

**CH0ERR ... CH3ERR
Channel-specific**

Byte	Bit 7 ... 0
0	Channel-specific error channel x: <ul style="list-style-type: none"> ■ Bit 0: set at configuring/parameter assignment error ■ Bit 2 ... 1: reserved ■ Bit 3: set at short-circuit to ground ■ Bit 7 ... 4: reserved

DIAG_US μ s ticker

Byte	Bit 7 ... 0
0...3	Value of the μ s ticker at the moment of the diagnostic <ul style="list-style-type: none"> ■ In the System MICRO module there is a timer (μs ticker). With PowerON the timer starts counting with 0. After $2^{32}-1\mu$s the timer starts with 0 again.

4.5.3 Technical data

Order no.	M32-1BD70
Type	SM M32 - Analog output
Module ID	050A 25E0
Current consumption/power loss	
Current consumption from backplane bus	60 mA
Current consumption from load voltage L+ (without load)	25 mA
Power loss	0.9 W
Technical data analog outputs	
Number of outputs	4
Cable length, shielded	200 mm
Rated load voltage	DC 24 V
Reverse polarity protection of rated load voltage	✓
Current consumption from rated load voltage	-
Voltage output short-circuit protection	✓
Voltage outputs	✓
Min. load resistance (voltage range)	5 kΩ
Max. capacitive load (current range)	1 μF
Max. inductive load (current range)	10 mA
Output voltage ranges	-10 V ... +10 V 0 V ... +10 V
Operational limit of voltage ranges	+/-0.3%
Basic error limit voltage ranges	+/-0.2%
Destruction limit against external applied voltage	max. 24V
Current outputs	-
Max. in load resistance (current range)	-
Max. inductive load (current range)	-
Typ. open circuit voltage current output	-
Output current ranges	-
Operational limit of current ranges	-
Basic error limit current ranges	-
Destruction limit against external applied voltage	-
Settling time for ohmic load	2 ms
Settling time for capacitive load	4 ms
Settling time for inductive load	-
Resolution in bit	12
Conversion time	2 ms all channels
Substitute value can be applied	no
Output data size	8 Byte

Order no.	M32-1BD70
Status information, alarms, diagnostics	
Status display	yes
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	yes
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	Bicolour green/red LED
Channel error display	red LED per channel
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	✓
Max. potential difference between circuits	-
Max. potential difference between inputs (Ucm)	-
Max. potential difference between Mana and Mintern (Uiso)	DC 75 V/ AC 50 V
Max. potential difference between inputs and Mana (Ucm)	-
Max. potential difference between inputs and Mintern (Uiso)	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	DC 500 V
Datasizes	
Input bytes	0
Output bytes	8
Parameter bytes	10
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm
Net weight	94 g
Weight including accessories	94 g
Gross weight	107 g
Environmental conditions	

Order no.	M32-1BD70
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes